

Properties of the weighted and robust implicitly weighted correlation coefficients

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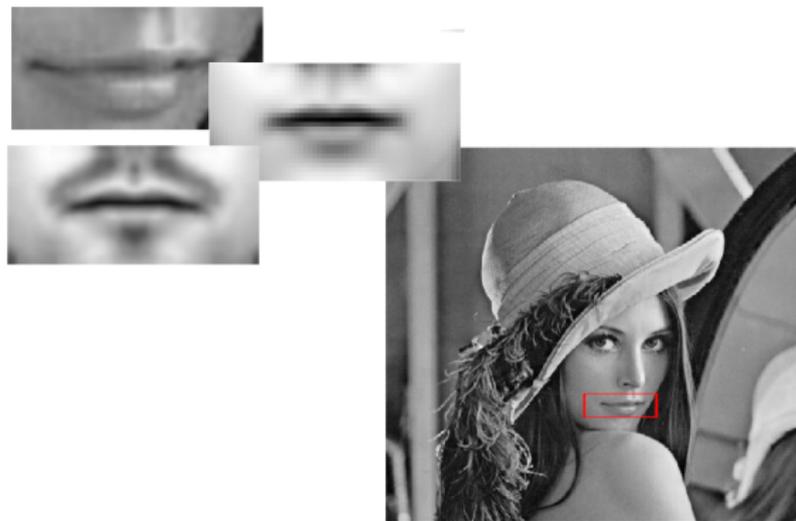
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Introduction

Template matching

- ▶ important part of computer vision algorithms
- ▶ searching for object or part of object in the image
- ▶ often performed in CNN feature space



Template matching

Sparse template

- ▶ templates can be sparse
- ▶ more efficient calculation



Template matching

Sub-tasks

- ▶ find optimal template/centroid
- ▶ find set of candidate regions
- ▶ evaluate the similarity between region and centroid

Similarity measures

- ▶ correlation coefficient
- ▶ Pearson product-moment correlation coefficient
 - ▶ similarity of two vectors
 - ▶ large variety of use cases
 - ▶ used in context of deep learning



Correlation coefficients

- ▶ r Pearson product-moment correlation coefficient

$$r = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum_{i=1}^n (x_i - \bar{x})^2} \sqrt{\sum_{i=1}^n (y_i - \bar{y})^2}}$$

- ▶ r_w weighted version of Pearson correlation coefficient
 - ▶ in some applications pairs of values are assigned **weights** (according measurement errors, position in image, etc.)

$$r = \frac{\sum_{i=1}^n w_i (x_i - \bar{x}_w)(y_i - \bar{y}_w)}{\sqrt{\sum_{i=1}^n w_i (x_i - \bar{x}_w)^2} \sqrt{\sum_{i=1}^n w_i (y_i - \bar{y}_w)^2}}$$



Energetic demands

Use on small devices

- ▶ need for low energy demands
- ▶ need for low memory demands
- ▶ various approximate computations are used

Upper and lower bounds for r_w

- ▶ one of results of our paper
- ▶ while using approximate versions of target vectors
- ▶ enables template matching on small devices



Modified image

Effect of modifying the image

- ▶ asymmetric illumination
- ▶ rotation

Result

- ▶ object localisation based on template matching with r_w is robust only to very small rotations of the image
- ▶ it is also vulnerable to illumination
- ▶ this may be argument for moving template matching to feature space (derived by CNN)



LWS-based robust correlation coefficient

LWS-based robust correlation coefficient

- ▶ variant of weighted correlation coefficient
- ▶ more robust
- ▶ based on Least Weighted Squares regression

Kalina, J.: Robust coefficients of correlation or spatial autocorrelation based on implicit weighting. *Journal of the Korean Statistical Society* 51, 1247-1267 (2022)

LWS estimator

- ▶ linear regression
- ▶ weight function - non-increasing continuous function

$$\psi : [0, 1] \rightarrow [0, 1], \text{ where } \psi(0) = 1, \psi(1) = 0$$



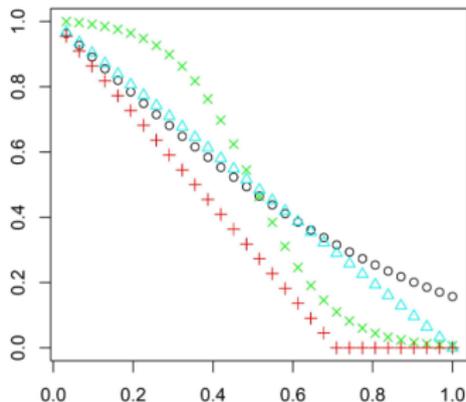
LWS-based robust correlation coefficient

LWS estimator

- ▶ LWS estimator is defined as

$$\arg \min_{b \in \mathbb{R}^d} \sum_{i=1}^n w_i u_{(i)}^2(b)$$

- ▶ residuals $u_{(i)}^2(b)$ are arranged in ascending order



LWS-based robust correlation coefficient

Definition

- ▶ regression task

$$y_i = \beta_0 + \beta_1 x_i + e_i$$

- ▶ r_{LWS} :

$$r_{LWS}(x, y) = r_{LWS}(x, y, \tilde{w})$$

- ▶ \tilde{w} optimal permutation of weights given by LWS

Properties

- ▶ highly robust alternative to r especially with respect to outliers



Hypothesis test based on r_{LWS}

Hypothesis about correlation coefficient

- ▶ Null hypothesis H_0 : There is no significant correlation between the variables ($\rho = 0$)
- ▶ Alternate hypothesis H_1 : There is a significant correlation between the variables ($\rho \neq 0$).

Test statistic T

$$T_{LWS} = \frac{r_{LWS}(x, y)}{\sqrt{1 - r_{LWS}^2(x, y)}} \sqrt{n - 2}$$

- ▶ asymptotically random variable with normal distribution



Hypothesis test based on r_{LWS}

Test result

$$H_0 \text{ is rejected} \iff |T_{LWS}| \geq z_{1-\alpha/2}$$

Test based on r_{LWS} and the Fisher transform

- ▶ test statistic

$$Z_{LWS} = \frac{1}{2} \log \left(\frac{1 + r_{LWS}}{1 - r_{LWS}} \right)$$

- ▶ test result

$$H_0 \text{ is rejected} \iff Z_{LWS}/SD(Z_{LWS}) \geq z_{1-\alpha/2}$$



Conclusion

- ▶ correlation coefficient and its weighted versions used in many applications, including template matching
- ▶ several properties derived including using approximate centroids (templates)
- ▶ tools for hypothesis testing derived

Thank you!

