## On the Unification of Term Schemata

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## Introduction

- Our motivation for studying unification over term sequences (term schemata) arose from our investigation concerning automated proof analysis in the presence of induction.
- An analysis of Fürstenburg's proof of the infinitude of primes was performed using a rudimentary schematic formalism and the first-order CERES method [Baaz et al., 2008].
  - This analysis was performed without a formal framework for schematic objects.
- Since this early work several attempts have been made to develop a formal framework for proof sequences as well as their analysis [Dunchev *et al.*, 2013], [Leitsch *et al.*, 2017], [Cerna *et al.*, 2019].



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 $\begin{array}{c} \Delta_1 \sigma' \vdash \Pi_1 \sigma' \quad \Delta_2 \tau \vdash \Pi_2 \tau \\ \varphi \\ \varphi \\ \Delta \sigma \vdash \Pi \sigma \end{array}$ 

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## Analysis of Schematic Proofs

- With enough effort a mathematical proof can be formalized within a logical calculus such as Gentzen's sequent calculus.
- This formalization process will likely result in a proof with cut rather than an analytic proof.

$$\frac{\textbf{C}, \Delta \vdash \Gamma}{\Delta, \Delta' \vdash \Gamma, \Gamma'} \text{ cut}$$

- Simulates lemmata and external theory introduction.
- Analysis of proofs concerns manipulation of the cut structure.
- Elimination of the cut structure results in an analytic proof.
- Such proofs provide additional mathematical understanding.

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**Global cut-elimination** produces an intermediate representation of a formal proof's cut-structure.

- From this intermediate representation a new proof with a **trivial cut-structure** is produced.
- CERES transforms the cut structure into a NNF formula which can be refuted using resolution.

## Local Cut-elimination and Schematic Proofs

- No cut reduction rules exists for recursive calls.

$$\frac{-\frac{(\varphi,\cdots)}{\overline{C},\overline{\Delta}\vdash\Gamma}-\frac{(\varphi_j,\cdots)}{\overline{\Delta'\vdash\Gamma'},\overline{C}}}{\Delta,\Delta'\vdash\Gamma,\Gamma'} \operatorname{cut}$$

- When the call structure is non-recursive, proof references can just be removed.
- Recursive calls block reduction of a cut formula's position in the proof.
- Using a global approach we can extract the cut-structure as an unsatisfiable, recursive negation normal form formula.

#### An Inductive Definition









- Proof references are denoted by defined symbols.
- Such a recursive NNF formula is always unsatisfiable.
- Proof analysis requires refuting this recursive NNF in a finitely representable way.



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## Example of an Recursive NNF Formula

$$\begin{split} \hat{O}(x, y, n, m) &\Longrightarrow \hat{D}(x, n, m) \land \hat{P}(x, y, n, m) \\ \hat{D}(x, n, 0) &\Longrightarrow f(x) = \hat{S}(n, a) \lor f(x) < \hat{S}(n, a) \\ \hat{D}(x, n, s(m)) &\Longrightarrow f(\hat{S}(s(m), x) = \hat{S}(n, a) \lor f(x) < \hat{S}(n, a)) \land \hat{D}(x, n, m) \\ \hat{P}(x, y, 0, m) &\Longrightarrow \hat{C}(y, 0, m) \land f(a) \neq 0 \\ \hat{P}(x, y, s(n), m) &\Longrightarrow (\hat{C}(y, s(n), m)) \land (\hat{T}(x, n, m)) \land \hat{P}(x, z, n, m) \\ \hat{C}(x, n, 0) &\Longrightarrow f(x) \neq \hat{S}(n, a) \\ \hat{C}(x, n, s(m)) &\Longrightarrow f(\hat{S}(s(m), x)) \neq \hat{S}(n, a) \lor \hat{C}(x, n, m) \\ \hat{T}(x, n, 0) &\Longrightarrow f(x) \notin \hat{S}(s(n), a) \lor f(x) = \hat{S}(n, a) \lor f(x) < \hat{S}(n, a) \\ \hat{T}(x, n, s(m)) &\Longrightarrow f(\hat{S}(s(m), x)) \notin \hat{S}(s(n), a) \lor f(\hat{S}(s(m), x)) = \hat{S}(n, a) \lor f(x) < \hat{S}(n, a) \land \hat{T}(x, n, m) \\ \hat{S}(0, x) &\Longrightarrow x \\ \hat{S}(s(n), x) &\Longrightarrow suc(\hat{S}(s(n), x)) \end{split}$$

## Refuting Recursive NNF Formula

- In [Leitsch et al., 2017], the n-clause calculus of [Aravantinos et al., 2013] was used to construct refutations.
  - This method is completely automated.
- However, the method is limited in scope and most problems of mathematical interest lie beyond it.
  - The above NNF is an example.
- In [Cerna et al., 2019], we considered a semi-automated approach to dealing with the recursive NNF formula and designed a resolution calculus for this purpose.
- This required developing a theory of unification over schematic terms, what we will discuss for the rest of this talk.

- In a general sense, term schemata are nothing more than a finite representation of an infinite sequence of first-order terms s<sub>n</sub> where n is a numeric parameter.
- Syntactically, this sequence is represented by a term ŝ(n) where ŝ may contain defined symbols indexed by the numeric parameter n.
- Defined symbols have associated defining equations allowing normalization to defined symbol-free first-order terms upon parameter instantiation.
- ▶ Normalization is denoted  $\hat{s}(n)\downarrow_{\sigma} = s_{\alpha}$  where  $\sigma = \{n \rightarrow \alpha\}$  is a parameter substitution.

- Similarly, substitution schemata are finite representations of infinite sequences of first-order substitutions σ<sub>n</sub>.
- Syntactically, substitution schemata are denoted by  $\hat{\lambda}(n)$  and are sets of bindings  $\{X(n) \rightarrow \hat{s}(n)\}$  were  $\hat{s}(n)$  is a term schema.
- Normalization of a substitution schema reduces to normalization of its bindings and is denoted by λ̂(n)↓<sub>σ</sub>.
- Index variables are referred to as global variables and will be discussed in greater detail shortly.
- The bindings used to construct a substitution schema may also be of the form  $\{x \rightarrow \hat{s}(n)\}$ .

#### Definition

Given two term schemata  $\hat{s}(n)$  and  $\hat{t}(n)$  we define  $\hat{s}(n), \hat{t}(n)$  as unifiable if there exists a substitution schema  $\hat{\lambda}(n)$  such that  $\hat{s}(n)\hat{\lambda}(n)\downarrow_{\sigma} = \hat{t}(n)\hat{\lambda}(n)\downarrow_{\sigma}$  for all assignments  $\sigma$ .

- Depending on the types of variables allowed in  $\hat{\lambda}(n)$  and in  $\hat{s}(n)$  and  $\hat{t}(n)$ , we define two types of unification problems.
  - Simple term schema unification: Only first-order variables occur in λ̂(n), ŝ(n), and t̂(n)
  - ► Global term schema unification: Global variables may occur in Â(n), ŝ(n), and t̂(n).

▶ We assume a well-founded order < on the defined symbols.

#### Definition

Let  $\vec{x}$  be a tuple of first-order variables and n be a numeric parameter. A simple term schema is defined by primitive recursive definitions of the form

$$\begin{aligned} \hat{f}(\vec{x}, \mathbf{0}) &= g(\vec{x}), \\ \hat{f}(\vec{x}, s(n)) &= h(\vec{x}, n, z) \{ z \leftarrow \hat{f}(\vec{x}, n) \} \end{aligned}$$

where  $g(\vec{x})$  is a term over the variables  $\vec{x}$  and  $h(\vec{x}, n, z)$  is a term over the variables  $\vec{x}, z$  and the parameter n. If  $\hat{f}$  is not a <-minimal defined symbol then both  $g(\vec{x})$  and  $h(\vec{x}, n, z)$  may contain defined symbols  $\hat{u}$  with  $\hat{u} < \hat{f}$ .

We now provide a few examples.

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#### Example: Simple Term Schema

• The defining equations  $\hat{f}, \hat{f}_1$ , and  $\hat{g}$  are as follows:

$$\hat{f}(x,0) = h(a,a) \qquad \hat{f}(x,s(n)) = h(x,\hat{f}(x,n)) \hat{f}_1(x,y,0) = h(a,a) \qquad \hat{f}_1(x,y,s(n)) = h(x,\hat{f}(y,n)) \hat{g}(x,y,0) = h(a,a) \qquad \hat{g}(x,y,s(n)) = h(\hat{g}(x,y,n),y)$$

- Note that  $\hat{f}_1 > \hat{f}$ .
- The relation between ĝ and the other symbols is irrelevant.
- Consider the parameter assignment σ = {n → 2} and the evaluation of f̂<sub>1</sub>(x, y, n):

$$\begin{split} \hat{f}_1(x,y,n) \downarrow_\sigma &= \hat{f}_1(x,y,2) \downarrow = h(x,\hat{f}(y,1) \downarrow) = h(x,h(y,\hat{f}(x,0) \downarrow)) \\ &= h(x,h(y,h(a,a)) \end{split}$$

#### Simple Term Schema Unification

• using the term schema  $\hat{f}, \hat{f}_1$ , and  $\hat{g}$  we can define unification problems such as:

$$\hat{f}(x,n) \stackrel{?}{=} \hat{g}(y,y,n)$$

Note that σ<sub>0</sub> = {n → 0} and σ<sub>1</sub> = {n → 1} This problem evaluates to

$$\hat{f}(x,n)\downarrow_{\sigma_0} \stackrel{?}{=} \hat{\mathbf{g}}(y,y,n)\downarrow_{\sigma_0} \implies h(a,a) \stackrel{?}{=} h(a,a)$$
$$\hat{f}(x,n)\downarrow_{\sigma_1} \stackrel{?}{=} \hat{\mathbf{g}}(y,y,n)\downarrow_{\sigma_1} \implies h(x,h(a,a)) \stackrel{?}{=} h(h(a,a),y)$$

Both of which are unifiable.

• However, for  $\sigma_2 = \{n \rightarrow 2\}$  it evaluates to

$$h(x, h(x, h(a, a))) \stackrel{?}{=} h(h(h(a, a), y), y)$$

► After two steps unification fails due to occurs check.

### Simple Term Schema Unification

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- For two term schemata to be unifiable, they must be unifiable for all parameter assignments.
- The following unification problem is actually unifiable:

$$\hat{f}_1(x,y,s(n)) \stackrel{?}{=} \hat{g}(z,z,s(n))$$

• Let us evaluate the term schema for  $\sigma_2 = \{n \rightarrow 2\}$ :

$$h(x, h(y, h(y, h(a, a)))) = h(h(h(h(a, a), z), z), z)$$

A unifier (also MGU) for this problem is as follows:

$$\theta = \{x \leftarrow h(h(h(a, a), h(y, h(y, h(a, a)))), h(y, h(y, h(a, a)))), \\z \leftarrow h(y, h(y, h(a, a)))\}.$$

The substitution schema (also the MGUSchema) is as follows:

$$\hat{\vartheta}(n) = \{x \leftarrow \hat{\mathbf{g}}(\hat{f}(y,n),\hat{f}(y,n),n), \ z \leftarrow \hat{f}(y,n)\}.$$

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#### From Simple to Global Term Schemata

- Notice that simple term schemata repeat a finite set of variables arbitrarily often.
- ► This results in occurrence check failure in many cases.
- Usually, we do not desire all variables occurrences to be the same nor do we desire them to all be different.
- These extreme cases can be described through quantification:

$$\hat{f}(x,n) \equiv \forall xh(x,h(x,\cdots,h(x,h(a,a))\cdots))$$

$$\hat{f}(x,n) \equiv \forall x_1, \cdots x_n h(x_1, h(x_2, \cdots, h(x_n, h(a, a)) \cdots))$$

- Global variables, variables taking numeric arguments,
- are a way of integrating indexing into the object language.
- This allows us to syntactically describe properties of the quantifier prefix.

Additionally, it reduces unwanted occurrence check failure.

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#### Definition

Let  $\vec{X}$  be a tuple of global variables and *n* be a numeric parameter. A global term schema is defined by primitive recursive definitions of the form

$$\hat{f}(\vec{X}, \mathbf{0}) = t(\vec{X}), \hat{f}(\vec{X}, s(n)) = s(\vec{X}, n, z) \{ z \leftarrow \hat{f}(\vec{X}, n) \}$$

where  $t(\vec{X})$  is a term over the global variables  $\vec{X}$  and  $s(\vec{X}, n, z)$  is a term over the global variables  $\vec{X}$ , the individual variable z and the parameter n. If  $\hat{f}$  is not a minimal defined symbol then both  $t(\vec{X})$  and  $s(\vec{X}, n, z)$  may contain defined symbols  $\hat{u}$  with  $\hat{u} < \hat{f}$ .

- Notice that the domain of a unifier of global term schemata is dependent on the numeric parameter.
- ▶ We refer to such unifiers as s-unifiers (schematic unifiers).

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#### From Simple to Global Term Schemata

Consider the following global term schema:

 $\hat{f}(X, \mathbf{0}) = h(a, X(0)) \qquad \hat{f}(X, s(n)) = h(X(s(n)), \hat{f}(X, n))$  $\hat{g}(X, \mathbf{0}) = h(X(0), a) \qquad \hat{g}(X, s(n)) = h(\hat{g}(X, n), X(s(n)))$  $\blacktriangleright \text{ Consider the unification problem } \hat{f}(X, s(n)) \stackrel{?}{=} \hat{g}(X, s(n)).$  $\vdash \text{ Evaluating this problem using } \sigma = \{n \to 1\} \text{ results in}$ 

 $h(X(2), h(X(1), h(a, X(0))) \stackrel{?}{=} h(h(h(X(0), a), X(1)), X(2))$ 

Note that the following is a unifier:

 $\theta = \{ \textbf{X(0)} \rightarrow a \ , \ \textbf{X(1)} \rightarrow \textbf{h}(a,a) \ , \ \textbf{X(2)} \rightarrow \textbf{h}(\textbf{h}(a,a),\textbf{h}(a,a)) \}$ 

• The s-unifier is  $\hat{\theta}(n) = \bigcup_{i=0}^{n} \{ X(i) \to \hat{h}(i) \}$  where

$$\hat{h}(\mathbf{0}) = a$$
  $\hat{h}(s(n)) = h(\hat{h}(n), \hat{h}(n))$ 

- The above term schema definitions do not have the full expressive power of primitive recursion.
- ▶ The following defined functions increase the expressivity.

#### Definition

A term schema is called a standard schema if it contains

- equations of the form  $\hat{g}[\alpha, i](x_1, \ldots, x_\alpha) = x_i$  (where  $1 \le i \le \alpha$ ) for every projection function  $I_i^{\alpha} : \iota^{\alpha} \to \iota$  where  $I_i^{\alpha}(\beta_1, \ldots, \beta_n) = \beta_i$  and
- equations of the form  $\hat{h}[\alpha, c](x_1, \dots, x_{\alpha}) = c$  for every constant function of type  $\iota^{\alpha} \to \iota$ .

Here  $\hat{g}[\alpha, i], \hat{h}[\alpha, c]$  are  $\alpha$ -ary defined function symbols.

Is the unification problem for simple standard schemata of recursion depth ≤ 1 decidable?

- Would need to show that it is reducible to the equivalence problem of LOOP-1 programs.
- Is the unification problem for global standard schemata of recursion depth ≤ 1 decidable?
  - Similar to first question but the unifier's domain size may vary.
- Is the unification problem for simple and/or global free schemata decidable?
  - While less expressive than free schemata, this type of unification shows up in the resolution calculus described in [Cerna *et al.*, 2019].
- We conjecture that all three problems are decidable.

- Term schemata provide an interesting unification problem motivated by computational proof analysis.
- We have yet to consider the equational variants of the above mentioned unification problems.
- It is also unclear if it is a variant of an existing unification problem such as term-graph unification or higher-order unification. Though we doubt the latter case.
- The notion of an MGU schema as well as how s-unifiers may be put in relation has not yet been formalized. Currently we are investigating this matter.