Towards A New Type of Prover: On the Benefits of Discovering Sequences of "Related" Proofs

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- Disclaimer: This investigation is in a very early stage.
- Essentially, we have just started looking for promising ways to circumvent a fundamental issue concerning the instance generalization prover VIPER.
 - The instance proofs need to be "related" and/or "uniform".
 - For some proof sequences this comes naturally.
 - For most it is anything but natural.
- In this talk we
 - Introduce the method,
 - Discuss its capabilities, and
 - Discuss characterizations of relatedness.

Induction: The Difficultly of Generalization

- Inductive theorem proving: find a pattern which follows from the provided axioms and can be used to prove any instance of the goal statement.
- This patterns is usually referred to as the induction invariant.
- As many here will probably know, invariant discovery is in general undecidable.
- Their exists weak theories of arithmetic where this problem is actually decidable, i.e. Pressburger arithmetic and [Aravantinos *et al.*, 2013].

- There are many different approaches to invariant discovery, we will only name a few:
 - Loop-Discovery Provers [Aravantinos et al., 2011]
 - Lemma Generation and testing [Claessen et al., 2013]
 - Rippling [Bundy et al., 2005]
 - Superposition based methods [Cruanes, 2015]
 - Cycle discovery [Brotherston, 2012]
 - and <u>Instance proof generalization</u> [Pearson, 1995] [Eberhard and Hetzl, 2015]
- This last approach will be the focus of this talk.

Background: Gentzen's Sequent Calculus

- The sequent calculus applies inferences to objects referred to as sequents Δ ⊢ Π, where Δ and Π are multisets of well-formed formula. Chaining inferences forms proof trees.
- Semantically a sequent means given Δ we may derive Π .
- Note that, this interpretation implies that Δ is essentially a conjunction of formula and Π is a disjunction.
- The sequent calculus Inferences are as follows:

Axiom Inferences

$$A \vdash A$$
 Ax

Structural Inferences



Logical Inferences

$$\frac{\Gamma \vdash \Delta, D}{\neg D, \Gamma \vdash \Delta} \neg : \mathbf{I} \qquad \frac{D, \Gamma \vdash \Delta}{\Gamma \vdash \Delta, \neg D} \neg : \mathbf{r} \qquad \frac{C, \Gamma \vdash \Delta}{C \land D, \Gamma \vdash \Delta} \land : \mathbf{I}$$
$$\frac{D, \Gamma \vdash \Delta}{C \land D, \Gamma \vdash \Delta} \land : \mathbf{I} \qquad \frac{\Gamma \vdash \Delta, C}{\Gamma \vdash \Delta, C \lor D} \lor : \mathbf{r} \qquad \frac{\Gamma \vdash \Delta, D}{\Gamma \vdash \Delta, C \lor D} \lor : \mathbf{r}$$
$$\frac{\Gamma \vdash \Delta, C}{\Gamma \vdash \Delta, C \land D} \land : \mathbf{r} \qquad \frac{C, \Gamma \vdash \Delta}{C \lor D, \Gamma \vdash \Delta} \lor : \mathbf{I}$$
$$\frac{C, \Gamma \vdash \Delta, D}{\Gamma \vdash \Delta, C \land D} \rightarrow : \mathbf{r} \qquad \frac{\Gamma \vdash \Delta, C}{C \lor D, \Gamma \vdash \Delta} \rightarrow : \mathbf{I}$$

Quantifier Inferences

$$\frac{\Gamma \vdash \Delta, F(\alpha)}{\Gamma \vdash \Delta, \forall x F(x)} \forall : \mathsf{r} \qquad \frac{F(t), \Gamma \vdash \Delta}{\forall x F(x), \Gamma \vdash \Delta} \forall : \mathsf{I}$$

$$\frac{\Gamma \vdash \Delta, F(t)}{\Gamma \vdash \Delta, \exists x F(x)} \exists : r \qquad \qquad \frac{F(\alpha), \Gamma \vdash \Delta}{\exists x F(x), \Gamma \vdash \Delta} \exists : I$$

Note that for ∃ : *I* and ∀ : *r* α may not occur in Γ or Δ. These rules are referred to as Strong quantification, i.e. require an eigenvariable, the other rules are referred to as Weak.

Quantifier Inferences

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Equational Axioms

$$F_{k} = x \operatorname{Re} \left[\begin{array}{c} \overline{x_{1} = y_{1}, \cdots, x_{n} = y_{n}, P(x_{1}, \cdots, x_{n}) \vdash P(y_{1}, \cdots, y_{n})} \end{array} \right] P_{=} \left[\begin{array}{c} \overline{x_{1} = y_{1}, \cdots, x_{n} = y_{n} \vdash f(x_{1}, \cdots, x_{n}) = f(y_{1}, \cdots, y_{n})} \end{array} \right] f_{=} \left[\begin{array}{c} \overline{x_{1} = y_{1}, \cdots, x_{n} = y_{n} \vdash f(x_{1}, \cdots, x_{n}) = f(y_{1}, \cdots, y_{n})} \end{array} \right] f_{=} \left[\begin{array}{c} \overline{x_{1} = y_{1}, \cdots, x_{n} = y_{n} \vdash f(x_{1}, \cdots, x_{n}) = f(y_{1}, \cdots, y_{n})} \end{array} \right] f_{=} \left[\begin{array}{c} \overline{x_{1} = y_{1}, \cdots, x_{n} = y_{n} \vdash f(x_{1}, \cdots, x_{n}) = f(y_{1}, \cdots, y_{n})} \end{array} \right] f_{=} \left[\begin{array}{c} \overline{x_{1} = y_{1}, \cdots, x_{n} = y_{n} \vdash f(x_{1}, \cdots, x_{n}) = f(y_{1}, \cdots, y_{n})} \end{array} \right] f_{=} \left[\begin{array}{c} \overline{x_{1} = y_{1}, \cdots, x_{n} = y_{n} \vdash f(x_{1}, \cdots, x_{n}) = f(y_{1}, \cdots, y_{n})} \end{array} \right] f_{=} \left[\begin{array}{c} \overline{x_{1} = y_{1}, \cdots, x_{n} = y_{n} \vdash f(x_{1}, \cdots, x_{n}) = f(y_{1}, \cdots, y_{n})} \end{array} \right] f_{=} \left[\begin{array}{c} \overline{x_{1} = y_{1}, \cdots, x_{n} = y_{n} \vdash f(x_{1}, \cdots, x_{n}) = f(y_{1}, \cdots, y_{n})} \end{array} \right] f_{=} \left[\begin{array}{c} \overline{x_{1} = y_{1}, \cdots, x_{n} = y_{n} \vdash f(x_{1}, \cdots, x_{n}) = f(y_{1}, \cdots, y_{n})} \end{array} \right] f_{=} \left[\begin{array}{c} \overline{x_{1} = y_{1}, \cdots, x_{n} = y_{n} \vdash f(x_{1}, \cdots, x_{n}) = f(y_{1}, \cdots, y_{n})} \end{array} \right] f_{=} \left[\begin{array}{c} \overline{x_{1} = y_{1}, \cdots, x_{n} = y_{n} \vdash f(x_{1}, \cdots, x_{n}) = f(y_{n}, \cdots, y_{n})} \end{array} \right] f_{=} \left[\begin{array}{c} \overline{x_{1} = y_{1}, \cdots, x_{n} = y_{n} \vdash f(x_{n}, \cdots, x_{n}) = f(y_{n}, \cdots, y_{n})} \end{array} \right] f_{=} \left[\begin{array}{c} \overline{x_{1} = y_{1}, \cdots, x_{n} = y_{n} \vdash f(x_{n}, \cdots, x_{n}) = f(y_{n}, \cdots, y_{n})} \end{array} \right] f_{=} \left[\begin{array}{c} \overline{x_{1} = y_{1}, \cdots, x_{n} = y_{n} \vdash f(x_{n}, \cdots, x_{n}) = f(y_{n}, \cdots, y_{n})} \end{array} \right] f_{=} \left[\begin{array}{c} \overline{x_{1} = y_{1}, \cdots, x_{n} = y_{n} \vdash f(x_{n}, \cdots, x_{n}) = f(y_{n}, \cdots, y_{n})} \end{array} \right] f_{=} \left[\begin{array}[c} \overline{x_{1} = y_{1}, \cdots, x_{n} = y_{n} \vdash f(x_{n}, \cdots, x_{n}) = f(y_{n}, \cdots, y_{n})} \end{array} \right] f_{=} \left[\begin{array}[c} \overline{x_{1} = y_{1}, \cdots, x_{n} = y_{n} \vdash f(x_{n}, \cdots, x_{n}) = f(y_{n}, \cdots, y_{n})} \end{array} \right] f_{=} \left[\begin{array}[c} \overline{x_{1} = y_{n}, \cdots, x_{n} = y_{n} \vdash f(x_{n}, \cdots, x_{n}) = f(y_{n}, \cdots, y_{n})} \end{array} \right] f_{=} \left[\begin{array}[c} \overline{x_{1} = y_{n}, \cdots, x_{n} = y_{n} \vdash f(x_{n}, \cdots, x_{n}) = f(y_{n}, \cdots, y_{n})} \end{array} \right] f_{=} \left[\begin{array}[c} \overline{x_{1} = y_{n}, \cdots, x_{n} = y_{n} \vdash f(x_{n}, \cdots, x_{n}) = f(y_{n}, \cdots, y_{n})} \end{array} \right] f_{=} \left[\begin{array}[c} \overline{x_$$

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Example Sequent Proof with Cut





Example Sequent Proof without Cut



Cannot eliminate atomic equational cuts.

Example Sequent Proof with Cut Sun Burst



Example Sequent Proof without Cut Sun Burst



- The theory of Peano arithmetic may by formalized as a theory extension of the LK-calculus with equality.
- Other than the axioms for successor, addition, and multiplication, one needs to add the following inference:

$$\frac{\mathsf{\Pi}\vdash\Delta,\varphi(\mathsf{0})\quad\mathsf{\Pi},\varphi(\alpha)\vdash\Delta,\varphi(s(\alpha))}{\mathsf{\Pi}\vdash\Delta,\varphi(\beta)}\mathsf{IND}$$

Alternatively one could consider adding the ω-rule which requires a proof of each instance of the main formula:

$$\frac{ \ \sqcap \vdash \Delta, \varphi(n) \quad \forall n \in \mathbb{N} }{ \ \sqcap \vdash \Delta, \varphi(\beta) } \omega$$

Without restrictions, the ω-rule is seemingly useless for practical cases.

- Fortunately, the primitive recursive ω-rule [J. Shoenfield 1959] is expressive enough to prove totality of all functions provably total in Peano arithmetic.
- Great a useful ω-rule, but how does one develop a finite description of a proof sequence?
- Maybe a little more specific, what can we do with φ(0), · · · , φ(n) for n < ∞?</p>
- This is the topic of "Inductive theorem proving based on tree grammars" by S. Eberhard and S. Hetzl (2015).

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Theorem (Mid-Sequent Theorem)

Let S be a sequent of prenex formulas then there exists a cut-free proof π of S s.t. π contains a sequent S' s.t.

- S' is quantifier free.
- Every inference above S' is structural or propositional.
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- S' is quantifier free.
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- Every inference below S' is structural or a quantifier inference.
- What if we limit S to a sequent only containing <u>weak</u> quantification.

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- No strong quantification means no <u>eigenvariables</u> and thus all terms are existential witnesses.
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Let S be a sequent of the form $\forall \bar{x} \varphi(\bar{x}) \vdash \exists \bar{x} \psi(\bar{x})$. S is valid if and only if there exists a sequence of term vectors $\bar{t}_1, \dots, \bar{t}_n$ s.t.

$$\bigwedge_{i=0}^k \varphi(\bar{t}_i) \vdash \bigvee_{i=0}^k \psi(\bar{t}_i)$$

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► Cut-free (weakly quantified end sequent) ⇒ weak mid-sequent ⇒ Herbrand instances.

Using First-Order Instance Proofs

- Let φ(β) be quantifier-free, Δ only contains weakly quantified formula, and Δ ⊢ φ(β) the main sequent of a sound application of the ω-rule.
- Furthermore, each of the instance proofs φ(n) for n ∈ N is provable without induction.
- We can ask a first-order theorem prover for a proof π_n of $\varphi(n)$.
- Each π_n is cut-free (atomic cuts don't count) and thus the Herbrand instances H_n may be extracted.
- At this point we can build a tree grammar G_n whose language is precisely H_n .
- Notice that G_n is specific to a particular π_n .

- This goes beyond the scope of this talk.
- For details please see "Inductive theorem proving based on tree grammars"
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- For details please see "Inductive theorem proving based on tree grammars"
- Essentially, a schematic tree grammar for a particular type of induction proof may be built from the instances... The right instances.
- Now comes the issues with the method.

Consider the problem

$$ADD, \forall x(x+0=0+x) \vdash \forall x(x+(x+x)=(x+x)+x)$$

- While simple Heuristics are enough to prove this statement, algorithmic ATP approaches tend to have a very difficult time with this simple problem, i.e [Aravantinos *et al.*, 2013].
- The tree grammar method discussed above manages to find the invariant

$$y + (x + x) = (x + x) + y$$

Congrats!

"Tree grammars for induction on inductive data types modulo equational theories" by G. Ebner and S. Hetzl

Now, let us try

$$ADD, MUL, \forall x(x * 0 = 0 * x) \vdash \forall x(x * (x * x) = (x * x) * x)$$

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Now, let us try failure, why?

$$ADD, MUL, \forall x(x * 0 = 0 * x) \vdash \forall x(x * (x * x) = (x * x) * x)$$

Example two: The 1-Strict Monotone Assertion (1-SMA)

A total monotonically decreasing (increasing) function f : N → B, B ⊆ Q, is said to be be k-strict monotone decreasing (increasing) if there exists at least k values in A s.t. f(a) = f(a + 1) for a ∈ A.

Assertion (1-SMA)

Every total monotonically decreasing function $f : \mathbb{N} \to \mathbb{N}$ is at least 1-strict monotone decreasing.



Combinatorially this statement encodes:

Number of objects in all ascending runs in the identity permutation of n ordered objects.

1-SMA Formalized and Solved

We formalize 1-SMA as an unsat inductive definition F: ∀n(∀x(f(g(x)) = n∨f(x) < n ∧∀x(f(x) = n∨f(x) < n) ∧Q̂(n)) where Q̂ is defined as follows:

$$\hat{Q}(0) \Rightarrow \neg f(a) < 0 \land \forall x(\neg f(x) = 0 \lor \neg f(g(x)) = 0) \hat{Q}(s(n)) \Rightarrow \forall x(\neg f(x) = s(n) \lor \neg f(g(x)) = s(n)) \land \forall x(\neg f(x) < s(n) \lor f(x) = n \lor f(x) < n) \land \forall x(\neg f(g(x)) < s(n) \lor f(g(x)) = n \lor f(x) < n) \land \hat{Q}(n))$$

 Viper, an implementation of the tree grammar prover, took (~ 5 hours), but manage to find the following invariant.

$$egin{aligned} (F\{n\leftarrow x\}
ightarrow (f(g(a))=0\lor f(a)=0\lor \hat{Q}(0)))\land \ &
onumber \ &$$

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When There is More Than One Way to Prove π_n

- For each successful example there are only a few ways to construct π_n.
- In truth there is only one proof modulo structural changes.
- This is not the case for the multiplication case.
- Two Instance proofs π_n and π_{n+1} may use the ADD theory and MUL theory in different ways.
- An even more important example as well as more problematic is the Non-Injectivity Assertion:

The formula F(n) is defined as follows:

$$\forall x \left(\bigvee_{i=0}^{n} f(x) = i \right) \land \left(\bigwedge_{i}^{n} \forall x \forall y \neg (s(x) \le y \land f(x) = i \land f(y) = i) \right)$$

 $\land \forall x \forall y \forall z (max(x, y) \leq z \rightarrow (x \leq z \land y \leq z)) \land \forall x (x \leq x)$

- ▶ Note that $\vdash \forall n \neg F(n)$ is provable in arithmetic.
- ▶ but there are many ways to prove $F(\alpha) \vdash$ for $\alpha \in \mathbb{N}$

SPASS Herbrand Instances F(2)



- These Herbrand instances where found using SPASS.
- If we compare this to the Herbrand instances found by cut-elimination for F(1) an issue arises.

Cut-elimination Herbrand Instances F(1)

- If you look closely (and know the problem) you will see that it is just counting natural numbers.
- It is not clear how counting natural number results in the instances for F(2).

SPASS Herbrand Instances F(1)

```
\langle g^2(U), g(U), max(g^2(U), g(U)) \rangle
1: \forall A_0 \forall B \forall C \langle g(U), g^2(U), max(g(U), g^2(U)) \rangle (\neg LEQ(max(A_0, B), C) \lor LEQ(B, C))
                      \langle g(U), g(U), max(g(U), g(U)) \rangle
                     \langle g^2(U), g(U), max(g^2(U), g(U)) \rangle
2: \forall A_0 \forall B \forall C \langle g(U), g^2(U), max(g(U), g^2(U)) \rangle ( \neg LEQ(max(A_0, B), C) \lor LEQ(A_0, C) )
                      \langle g(U), g(U), max(g(U), g(U)) \rangle
                   (g(U))
           \langle \max(g(U), g(U)) \rangle
                                         ( E(f(A), s(0)) ∨ E(f(A), 0) )
3: ∀A
             (U)
          ( \max(g^2(U), g(U)) )
          ( \max(g(U), g^2(U)) )
                   (g(U))
4: \forall A  ( \max(g(U), g(U)) ) 
( \max(g(U), g^2(U)) )  LEQ(A, A)
          ( \max(g^2(U), g(U)) )
                    \langle U, max(g^2(U), g(U)) \rangle
                           (U.g(U))
5: ∀B<sub>1</sub> ∀A<sub>2</sub>
                                                            ( ( \neg LEQ(g(B_1), A_2) \lor \neg E(f(B_1), s(0)) ) \lor \neg E(f(A_2), s(0)) )
                    (U, max(g(U), g(U)))
                 \langle g(U), max(g(U), g^2(U)) \rangle
                            (U,g(U))
                    (U, max(g(U), g(U)))
 \mathbf{6}: \forall \mathsf{B}_0 \forall \mathsf{A}_1 \quad (\mathsf{g}(\mathsf{U}), \mathsf{max}(\mathsf{g}^2(\mathsf{U}), \mathsf{g}(\mathsf{U}))) \land ((\neg \mathsf{LEQ}(\mathsf{g}(\mathsf{B}_0), \mathsf{A}_1) \lor \neg \mathsf{E}(\mathsf{f}(\mathsf{B}_0), \mathsf{0})) \lor \neg \mathsf{E}(\mathsf{f}(\mathsf{A}_1), \mathsf{0})) 
                    \langle U, max(g(U), g^2(U)) \rangle
```

Even simpler...

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The relationship between π_n and π_{n+1}

- Our example instance sets for F(1) and F(2) illustrate that the various proofs are not related.
- Thus, if we give the proofs to Viper the chance it will find an invariant is around 0.
- Can we develop a prover which generates sequences of proofs which are "Uniform".
- What do we mean by "uniform" anyway, What is "relatedness".
- Mathematically, are we trying to find proofs which use a particular trick and/or method.

Proposal: Can Modern Machine Learning Help?

- This is not a question about theorem proving, rather it is a "mathematical understanding"?
- Can we get the Theorem prover to understand what it ought to look for while constructing π_{n+1} using the proofs produced for π_n and below?
- ▶ We know the prover can prove π_{n+1}, but can it prove it in the right way!
- As mentioned earlier, this work is in its infancy.
 - A) I believe modern machine learning method may help solve the "uniformity" problem.
 - B) I don't know how they might help, maybe you do?
 - C) If interested and think you might have an idea, I would love to discuss it.
 - Currently looking for collaboration for a proposal I am developing.

Thank you for your time.