

# Efficient Estimation of the $A$ -norm of the Error in the Preconditioned Conjugate Gradient Method

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International Conference On Preconditioning, May 19-21, 2005.

Emory University, Atlanta, Georgia, U.S.A.



# A system of linear algebraic equations

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Consider a system of linear algebraic equations

$$\mathbf{A}x = b$$

where  $\mathbf{A} \in \mathbb{R}^{n \times n}$  is symmetric positive definite,  $b \in \mathbb{R}^n$ .

Discretization of elliptic partial differential equations: Energy norm.

The conjugate gradient method minimizes at the  $j$ th step the energy norm of the error on the given  $j$ -dimensional Krylov subspace.



# The conjugate gradient method (CG)

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Given  $x_0 \in \mathbb{R}^n$ ,  $r_0 = b - \mathbf{A}x_0$ .

CG computes a sequence of iterates  $x_j$ ,

$$x_j \in x_0 + \mathcal{K}_j(\mathbf{A}, r_0)$$

so that

$$\|x - x_j\|_{\mathbf{A}} = \min_{u \in x_0 + \mathcal{K}_j(\mathbf{A}, r_0)} \|x - u\|_{\mathbf{A}},$$

where

$$\mathcal{K}_j(\mathbf{A}, r_0) \equiv \text{span} \{r_0, \mathbf{A}r_0, \dots, \mathbf{A}^{j-1}r_0\},$$

$$\|x - x_j\|_{\mathbf{A}} \equiv \left( (x - x_j), \mathbf{A}(x - x_j) \right)^{\frac{1}{2}}.$$



# CG – Hestenes and Stiefel (1952)

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given  $x_0$ ,  $r_0 = b - \mathbf{A}x_0$ ,  $p_0 = r_0$ ,

for  $j = 0, 1, 2, \dots$

$$\gamma_j = \frac{(r_j, r_j)}{(p_j, \mathbf{A}p_j)}$$

$$x_{j+1} = x_j + \gamma_j p_j$$

$$r_{j+1} = r_j - \gamma_j \mathbf{A}p_j$$

$$\delta_{j+1} = \frac{(r_{j+1}, r_{j+1})}{(r_j, r_j)}$$

$$p_{j+1} = r_{j+1} + \delta_{j+1} p_j$$



# Preconditioned Conjugate Gradients (PCG)

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The CG-iterates are thought of being applied to

$$\hat{\mathbf{A}}\hat{x} = \hat{b}.$$

We consider symmetric preconditioning

$$\hat{\mathbf{A}} = \mathbf{L}^{-1}\mathbf{A}\mathbf{L}^{-T}, \quad \hat{b} = \mathbf{L}^{-1}b.$$

Change of variables

$$\mathbf{M} \equiv \mathbf{L}\mathbf{L}^T, \quad \gamma_j \equiv \hat{\gamma}_j, \quad \delta_j \equiv \hat{\delta}_j,$$

$$x_j \equiv \mathbf{L}^{-T}\hat{x}_j, \quad r_j \equiv \mathbf{L}\hat{r}_j, \quad s_j \equiv \mathbf{M}^{-1}r_j, \quad p_j \equiv \mathbf{L}^{-T}\hat{p}_j.$$

The preconditioner  $\mathbf{M}$  is chosen so that a linear system with the matrix  $\mathbf{M}$  is easy to solve while the matrix  $\mathbf{L}^{-1}\mathbf{A}\mathbf{L}^{-T}$  should ensure fast convergence of CG.



# Algorithm of PCG

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given  $x_0$ ,  $r_0 = b - \mathbf{A}x_0$ ,  $s_0 = \mathbf{M}^{-1}r_0$ ,  $p_0 = s_0$ ,

for  $j = 0, 1, 2, \dots$

$$\gamma_j = \frac{(r_j, s_j)}{(p_j, \mathbf{A}p_j)}$$

$$x_{j+1} = x_j + \gamma_j p_j$$

$$r_{j+1} = r_j - \gamma_j \mathbf{A}p_j$$

$$s_{j+1} = \mathbf{M}^{-1}r_{j+1}$$

$$\delta_{j+1} = \frac{(r_{j+1}, s_{j+1})}{(r_j, s_j)}$$

$$p_{j+1} = s_{j+1} + \delta_{j+1} p_j$$



# How to measure quality of approximation?

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... it depends on a problem.

- **using residual information,**
  - normwise backward error,
  - relative residual norm.
- **using error estimates,**
  - **estimate of the  $A$ -norm of the error,**
  - estimate of the Euclidean norm of the error.

If the system is well-conditioned - it does not matter.



# A message from history

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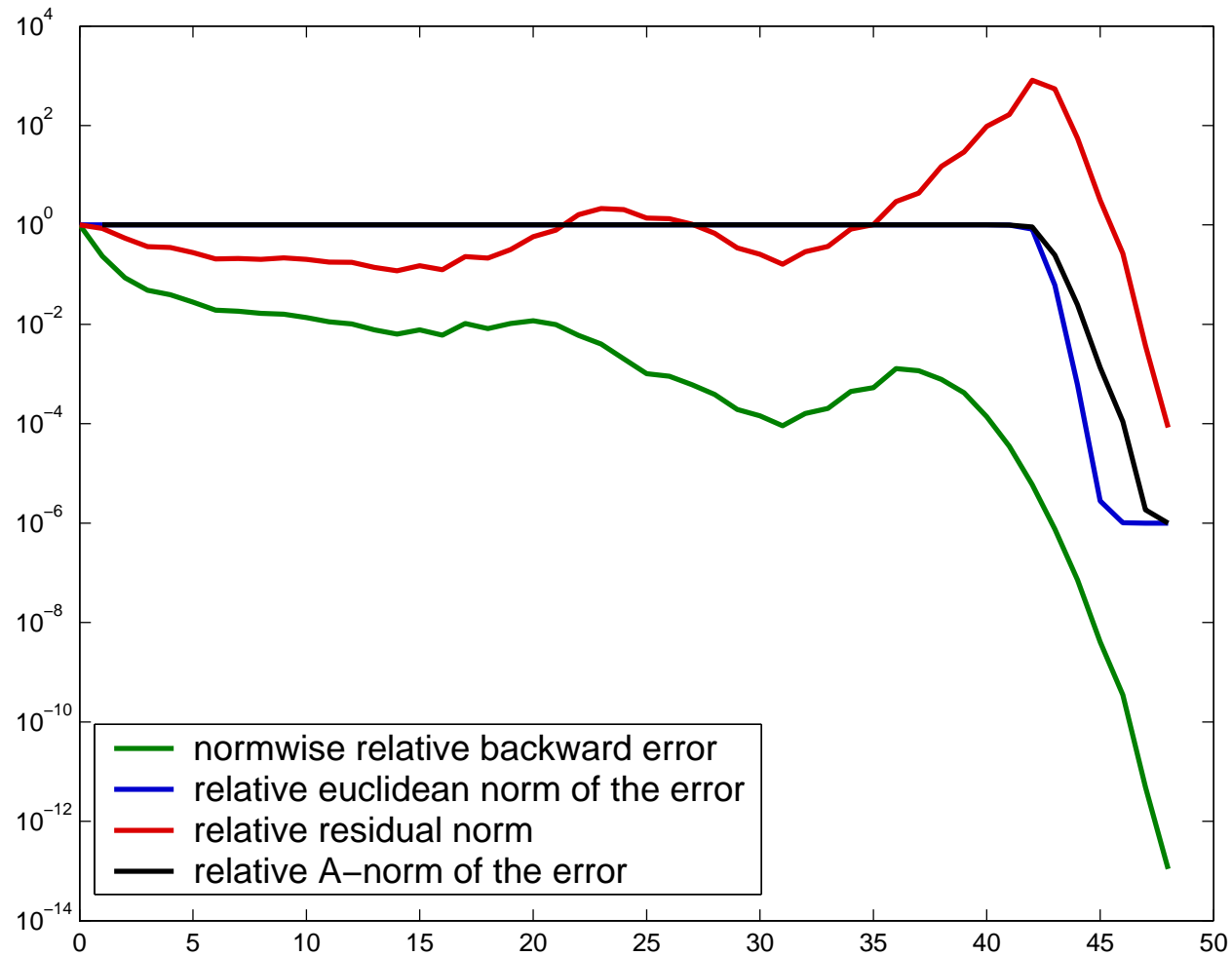
- Using of the residual vector  $r_j$  as a measure of the “goodness” of the estimate  $x_j$  is not reliable [HeSt-52, p. 410].
- The function  $(x - x_j, \mathbf{A}(x - x_j))$  can be used as a measure of the “goodness” of  $x_j$  as an estimate of  $x$  [HeSt-52, p. 413].





# Various convergence characteristics

Example using [GuSt-00],  $n = 48$ .





# Outline

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1. CG and Gauss Quadrature
2. Construction of estimates in CG and PCG
3. Estimates in finite precision arithmetic
4. Rounding error analysis
5. Numerical experiments
6. Conclusions



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# 1. CG and Gauss Quadrature



# CG and Gauss Quadrature

At any iteration step  $j$ , CG (implicitly) determines **weights** and **nodes** of the  $j$ -point Gauss quadrature

$$\int_{\zeta}^{\xi} f(\lambda) d\omega(\lambda) = \sum_{i=1}^j \omega_i^{(j)} f(\theta_i^{(j)}) + R_j(f).$$

For  $f(\lambda) \equiv \lambda^{-1}$  the formula takes the form

$$\frac{\|x - x_0\|_{\mathbf{A}}^2}{\|r_0\|^2} = \text{\textit{j-th Gauss quadrature}} + \frac{\|x - x_j\|_{\mathbf{A}}^2}{\|r_0\|^2}.$$

This formula was a base for CG error estimation in [DaGoNa-78, GoFi-93, GoMe-94, GoSt-94, GoMe-97, ...].



# Equivalent formulas

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- **Continued fractions** [GoMe-94, GoSt-94, GoMe-97]

$$\|r_0\|^2 C_n = \|r_0\|^2 C_j + \|x - x_j\|_{\mathbf{A}}^2,$$

$C_n, C_j \dots$  continued fractions corresponding to  $\omega(\lambda)$  and  $\omega^{(j)}(\lambda)$ .

- **Warnick** [Wa-00]

$$r_0^T (x - x_0) = r_0^T (x_j - x_0) + \|x - x_j\|_{\mathbf{A}}^2.$$

- **Hestenes and Stiefel** [HeSt-52, De-93, StTi-02]

$$\|x - x_0\|_{\mathbf{A}}^2 = \sum_{i=0}^{j-1} \gamma_i \|r_i\|^2 + \|x - x_j\|_{\mathbf{A}}^2.$$

The last formula is derived **purely algebraically!**



# Hestenes and Stiefel formula (derivation)

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Using local orthogonality between  $r_{i+1}$  and  $p_i$ ,

$$\|x - x_i\|_{\mathbf{A}}^2 - \|x - x_{i+1}\|_{\mathbf{A}}^2 = \gamma_i \|r_i\|^2.$$

Then

$$\begin{aligned} \|x - x_0\|_{\mathbf{A}}^2 - \|x - x_j\|_{\mathbf{A}}^2 &= \sum_{i=0}^{j-1} (\|x - x_i\|_{\mathbf{A}}^2 - \|x - x_{i+1}\|_{\mathbf{A}}^2) \\ &= \sum_{i=0}^{j-1} \gamma_i \|r_i\|^2. \end{aligned}$$

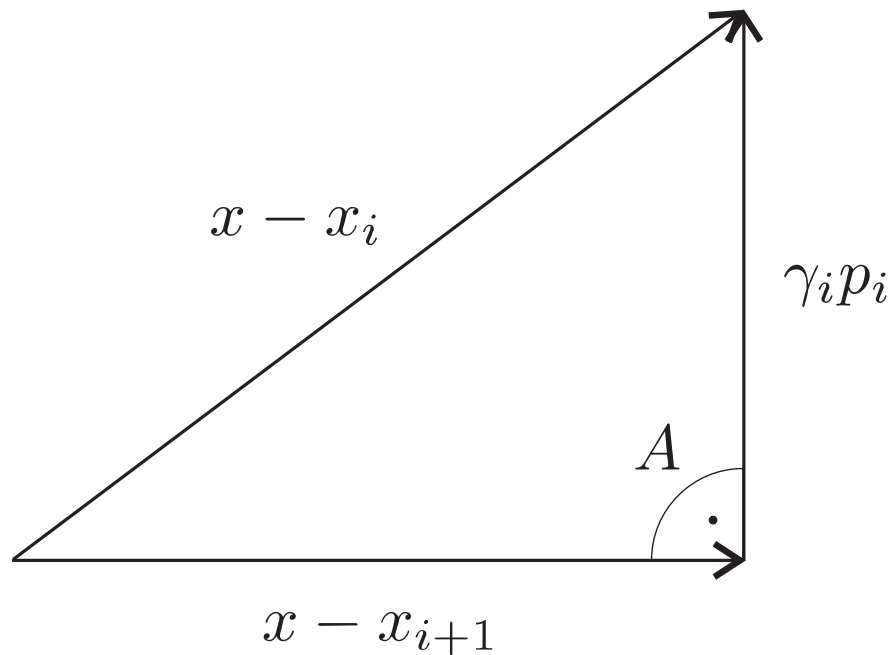
The approach to derivation of this formula is very important for its understanding in finite precision arithmetic.



# Local $A$ -orthogonality

Standard derivation of this formula uses global  $A$ -orthogonality among direction vectors [AxKa-01, p. 274], [Ar-04, p. 8].

A local  $A$ -orthogonality and Pythagorean theorem should be used instead:





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## 2. Construction of estimates in CG and PCG





# Construction of estimate in CG

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Idea: Consider, for example,

$$\|x - x_j\|_{\mathbf{A}}^2 = \|r_0\|^2 [C_n - C_j] .$$

Run  $d$  extra steps. Subtracting identity for  $\|x - x_{j+d}\|_{\mathbf{A}}^2$  gives

$$\|x - x_j\|_{\mathbf{A}}^2 = \underbrace{\|r_0\|^2 [C_{j+d} - C_j]}_{EST^2} + \|x - x_{j+d}\|_{\mathbf{A}}^2 .$$

When  $\|x - x_j\|_{\mathbf{A}}^2 \gg \|x - x_{j+d}\|_{\mathbf{A}}^2$ , we have a tight (lower) bound  
[GoSt-94, GoMe-97].



# Mathematically equivalent estimates

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- **Continued fractions** [GoSt-94, GoMe-97]

$$\eta_{j,d} = \|r_0\|^2 [C_{j+d} - C_j],$$

- **Warnick** [Wa-00]

$$\mu_{j,d} = r_0^T (x_{j+d} - x_j),$$

- **Hestenes and Stiefel** [HeSt-52]

$$\nu_{j,d} = \sum_{i=j}^{j+d-1} \gamma_i \|r_i\|^2.$$



# Construction of estimate in PCG

The  $\mathbf{A}$ -norm of the error can be estimated similarly as in ordinary CG.

- Extension of the Gauss Quadrature formulas based on continued fractions was published in [Me-99].
- Extension of the HS estimate: use the HS formula for  $\hat{\mathbf{A}}\hat{x} = \hat{b}$  and substitution  $\hat{\mathbf{A}} = \mathbf{L}^{-1}\mathbf{A}\mathbf{L}^{-T}$ ,  $\hat{x}_j = \mathbf{L}^T x_j$ ,  $\hat{\gamma}_i = \gamma_i$ ,  $\hat{r}_i = \mathbf{L}^{-1}r_i$  [De-93, AxKa-01, StTi-04, Ar-04]

$$\frac{\underbrace{\|\hat{x} - \hat{x}_j\|_{\hat{\mathbf{A}}}^2}_{\|x - x_j\|_{\mathbf{A}}^2}}{\|x - x_j\|_{\mathbf{A}}^2} = \sum_{i=j}^{j+d-1} \underbrace{\hat{\gamma}_i \|\hat{r}_i\|^2}_{\gamma_i (r_i, s_i)} + \frac{\underbrace{\|\hat{x} - \hat{x}_{j+d}\|_{\hat{\mathbf{A}}}^2}_{\|x - x_{j+d}\|_{\mathbf{A}}^2}}{\|x - x_{j+d}\|_{\mathbf{A}}^2}.$$

In many problems it is convenient to use a stopping criterion that relates the relative  $\mathbf{A}$ -norm of the error to a discretization error, see [Ar-04].



# Estimating the relative $\mathbf{A}$ -norm of the error

To estimate the relative  $\mathbf{A}$ -norm of the error we use the identities

$$\begin{aligned}\|x - x_j\|_{\mathbf{A}}^2 &= \nu_{j,d} + \|x - x_{j+d}\|_{\mathbf{A}}^2, \\ \|x\|_{\mathbf{A}}^2 &= \underbrace{\nu_{0,j+d} + 2b^T x_0 - \|x_0\|_{\mathbf{A}}^2}_{\xi_{j+d}} + \|x - x_{j+d}\|_{\mathbf{A}}^2.\end{aligned}$$

Define

$$\varrho_{j,d} \equiv \frac{\nu_{j,d}}{\xi_{j+d}}.$$

If  $\|x\|_{\mathbf{A}} \geq \|x - x_0\|_{\mathbf{A}}$  then  $\varrho_{j,d} > 0$  and

$$\varrho_{j,d} = \frac{\|x - x_j\|_{\mathbf{A}}^2 - \|x - x_{j+d}\|_{\mathbf{A}}^2}{\|x\|_{\mathbf{A}}^2 - \|x - x_{j+d}\|_{\mathbf{A}}^2} \leq \frac{\|x - x_j\|_{\mathbf{A}}^2}{\|x\|_{\mathbf{A}}^2}.$$



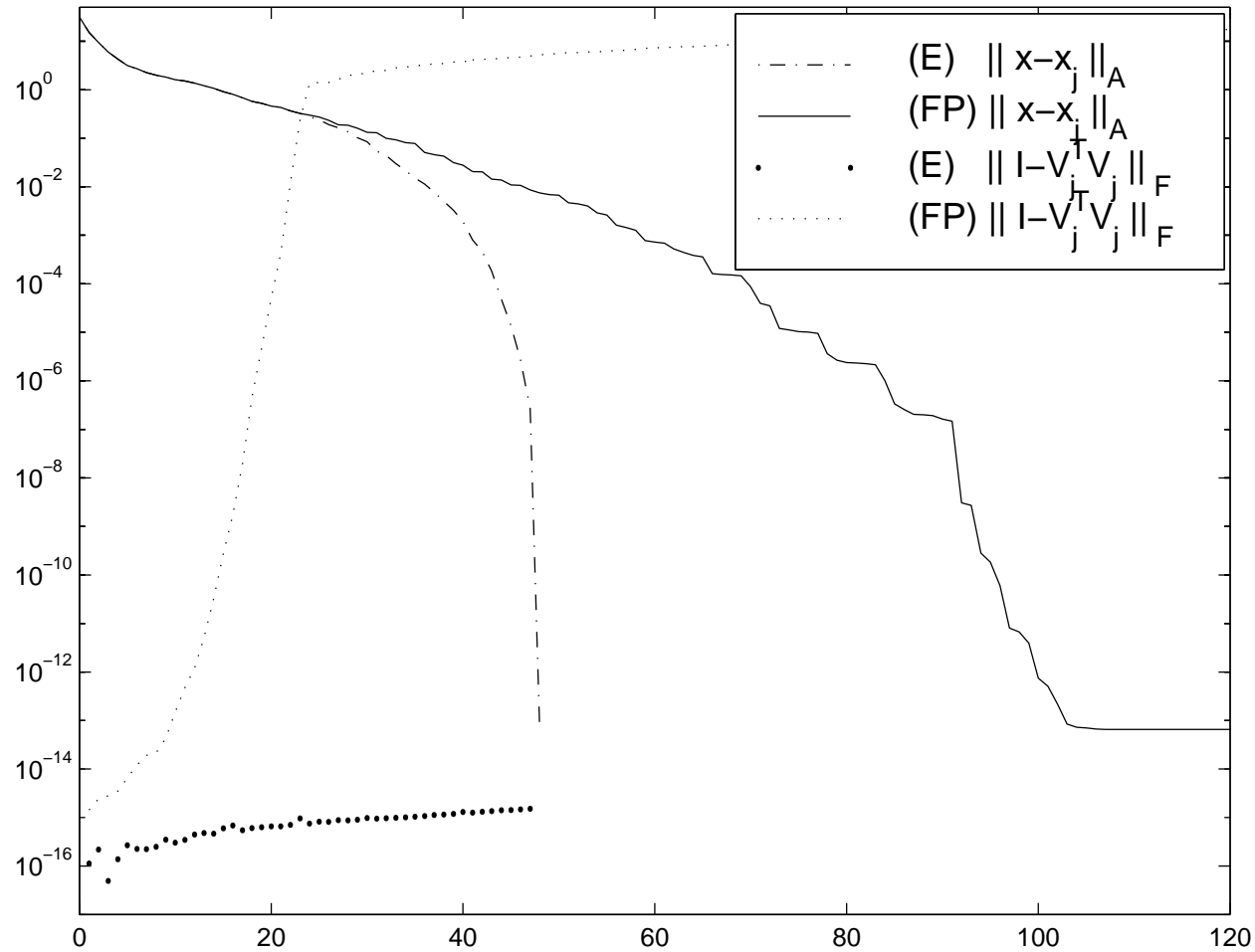
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### 3. Estimates in finite precision arithmetic



# CG behavior in finite precision arithmetic

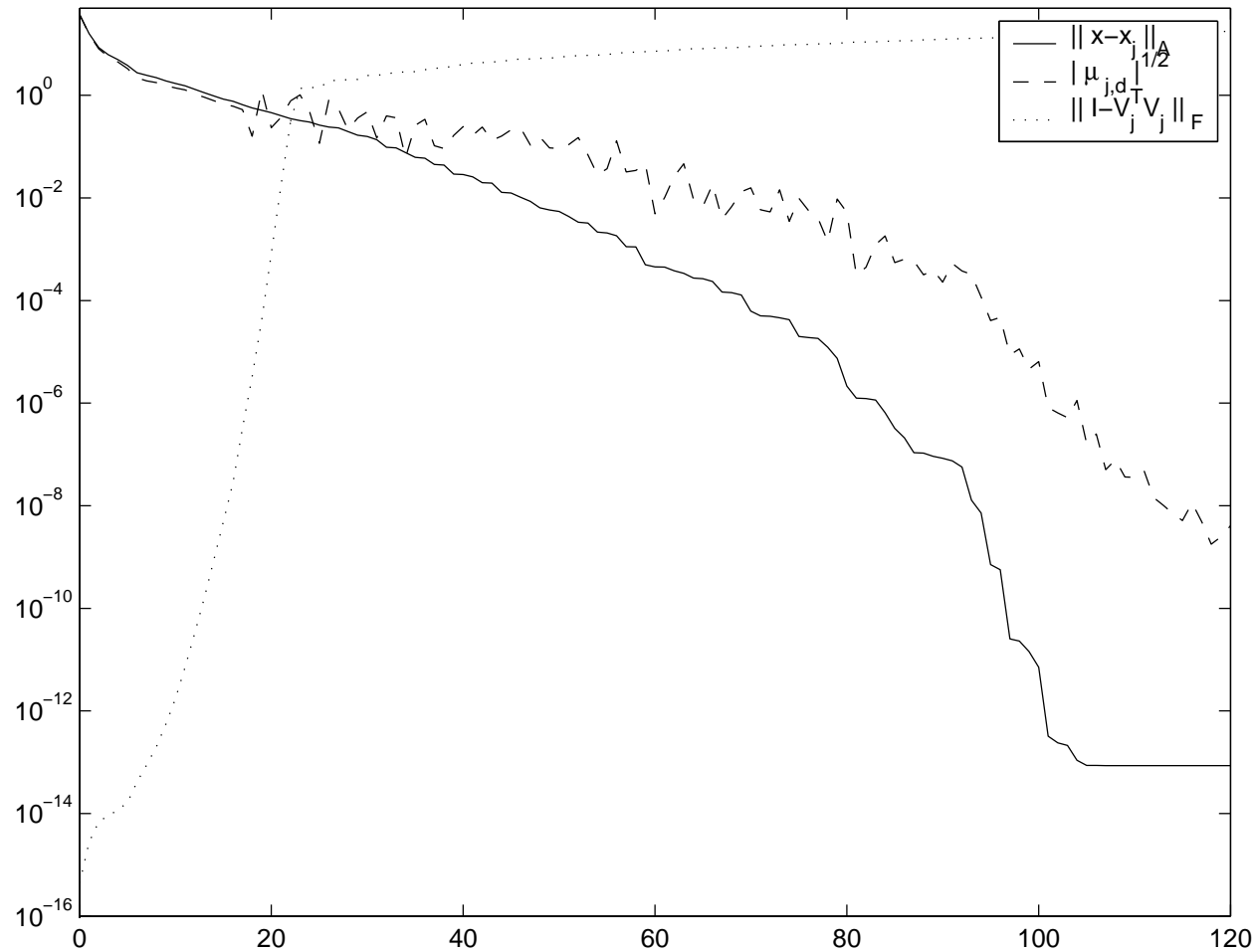
orthogonality is lost, convergence is delayed!





# Estimates need not work

The identity  $\|x - x_j\|_{\mathbf{A}}^2 = EST^2 + \|x - x_{j+d}\|_{\mathbf{A}}^2$  need not hold during the finite precision CG computations. An example:  $\mu_{j,d} = r_0^T (x_{j+d} - x_j)$  does not work!





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## 4. Rounding error analysis





# Rounding error analysis

Without a proper rounding error analysis, there is no justification that the proposed estimates will work in finite precision arithmetic.

Do the estimates give good information in practical computations?

estimate	CG	PCG	
$\eta_{j,d}$ (continued fractions)	<b>yes</b> *	<b>yes?</b>	[GoSt-94, GoMe-97, Me-99]
$\mu_{j,d}$ (Warnick)	<b>no</b>	<b>no</b>	[StTi-02]
$\nu_{j,d}$ (Hestenes and Stiefel)	<b>yes</b>	<b>yes</b>	[StTi-02, StTi-04]

\*Based on [GrSt-92], [Gr-89],  $\sqrt{\varepsilon}$  limit.



# Hestenes and Stiefel estimate (CG)

[StTi-02]: Rounding error analysis based on

- detailed proof of preserving local orthogonality in CG,
- results [Pa-71, Pa-76, Pa-80], [Gr-89, Gr-97].

**Theorem:** Let  $\varepsilon \kappa(\mathbf{A}) \ll 1$ . Then the CG approximate solutions computed in finite precision arithmetic satisfy

$$\|x - x_j\|_{\mathbf{A}}^2 - \|x - x_{j+d}\|_{\mathbf{A}}^2 = \nu_{j,d} + \|x - x_j\|_{\mathbf{A}} E_{j,d} + \mathcal{O}(\varepsilon^2),$$
$$|E_{j,d}| \approx (\sqrt{\kappa(A)}) \varepsilon \|x - x_0\|_{\mathbf{A}}.$$

**Main result:** Until  $\|x - x_j\|_{\mathbf{A}}$  reaches a level close to  $\varepsilon \|x - x_0\|_{\mathbf{A}}$ , the estimate  $\nu_{j,d}$  **must work**.



# Hestenes and Stiefel estimate (PCG)

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[StTi-04]: Analysis based on:

- rounding error analysis from [StTi-02],
- solving of

$$\mathbf{M}s_{j+1} = r_{j+1}$$

enjoys perfect normwise backward stability [Hi-96, p. 206].

Similar result as for CG: Until  $\|x - x_j\|_{\mathbf{A}}$  reaches a level close to  $\varepsilon \|x - x_0\|_{\mathbf{A}}$ , the estimate

$$\nu_{j,d} = \sum_{i=j}^{j+d-1} \gamma_i(r_i, s_i)$$

must work.



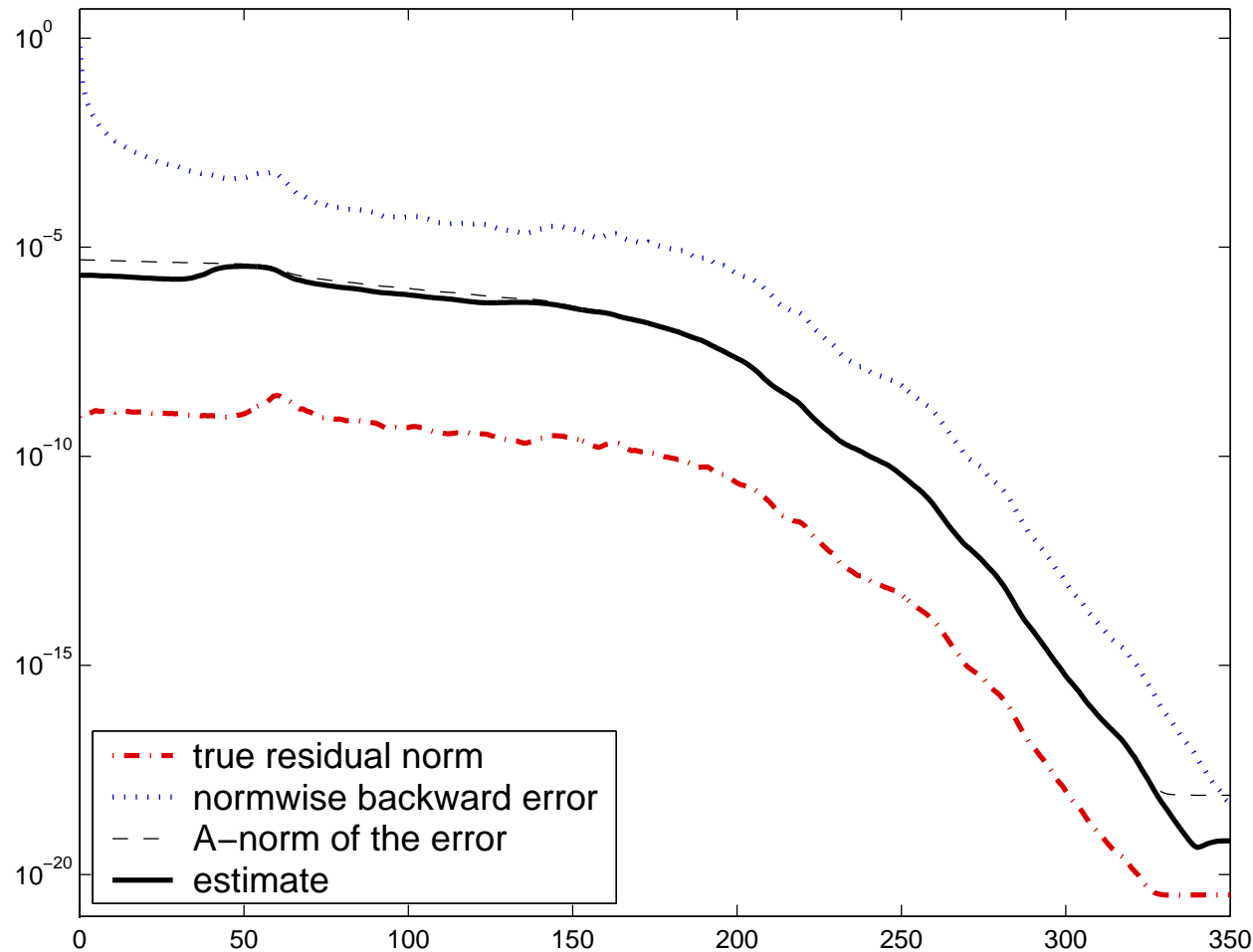
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## 5. Numerical Experiments



# Estimating the $\mathbf{A}$ -norm of the error

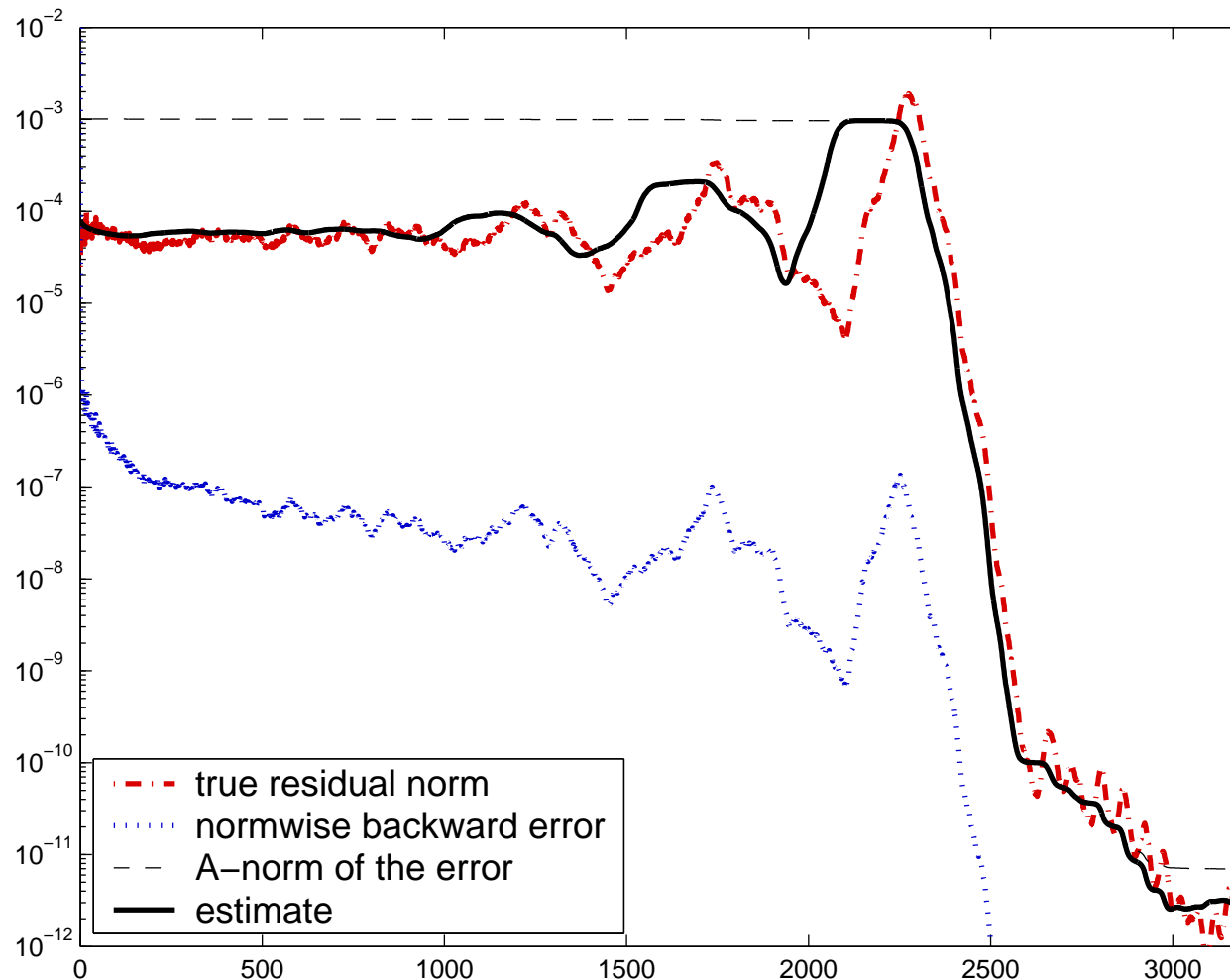
P. Benner: Large-Scale Control Problems, optimal cooling of steel profiles, **PCG**,  $\kappa(\mathbf{A}) = 9.7e + 04$ ,  $n = 5177$ ,  $d = 4$ ,  $\mathbf{L} = \text{cholinc}(\mathbf{A}, 0)$ .





# Estimating the $\mathbf{A}$ -norm of the error

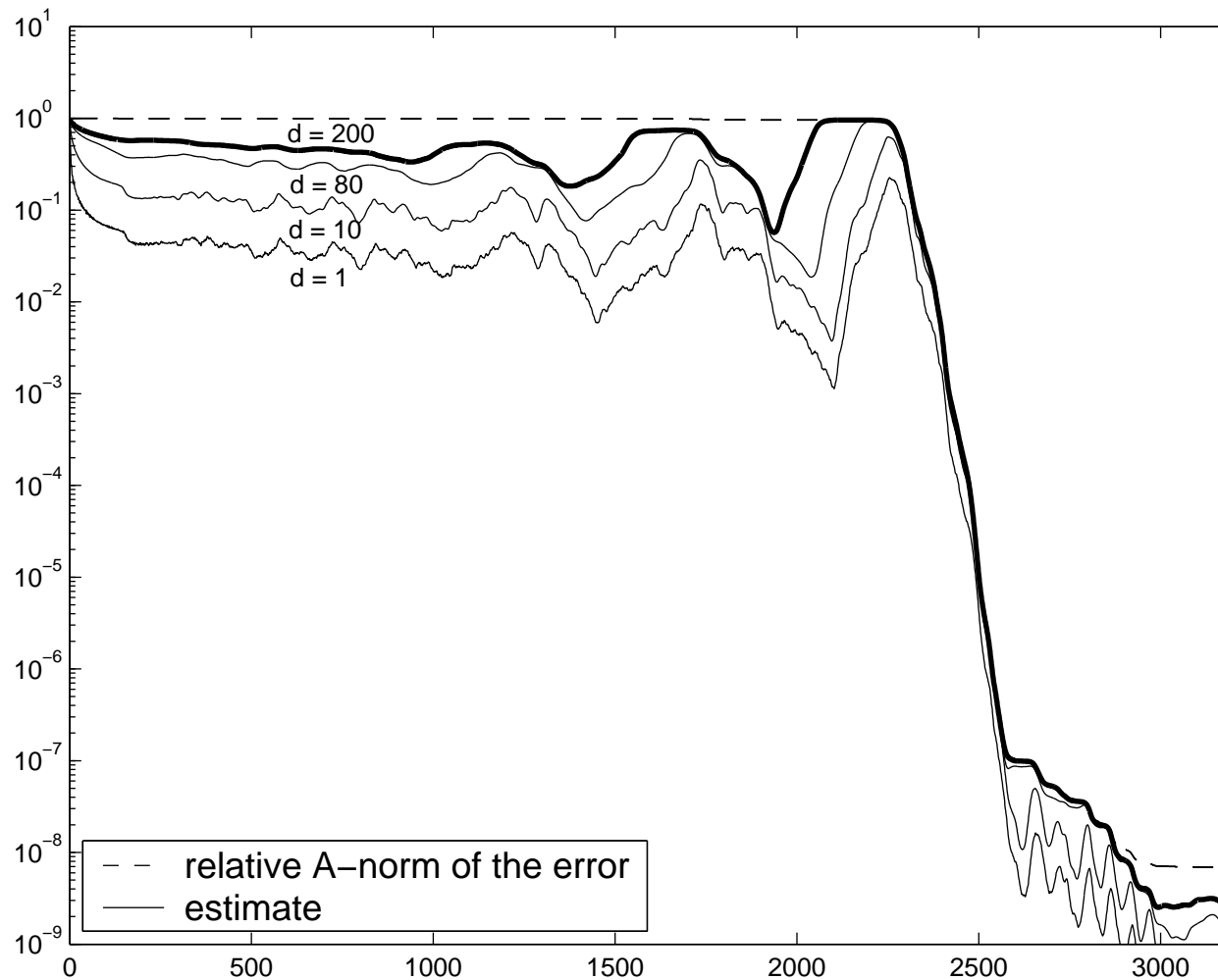
R. Kouhia: Cylindrical shell (Matrix Market), matrix s3dkt3m2,  
**PCG**,  $\kappa(\mathbf{A}) = 3.62e + 11$ ,  $n = 90499$ ,  $d = 200$ ,  $\mathbf{L} = \text{cholinc}(\mathbf{A}, 0)$ .





# Estimating the relative $A$ -norm of the error

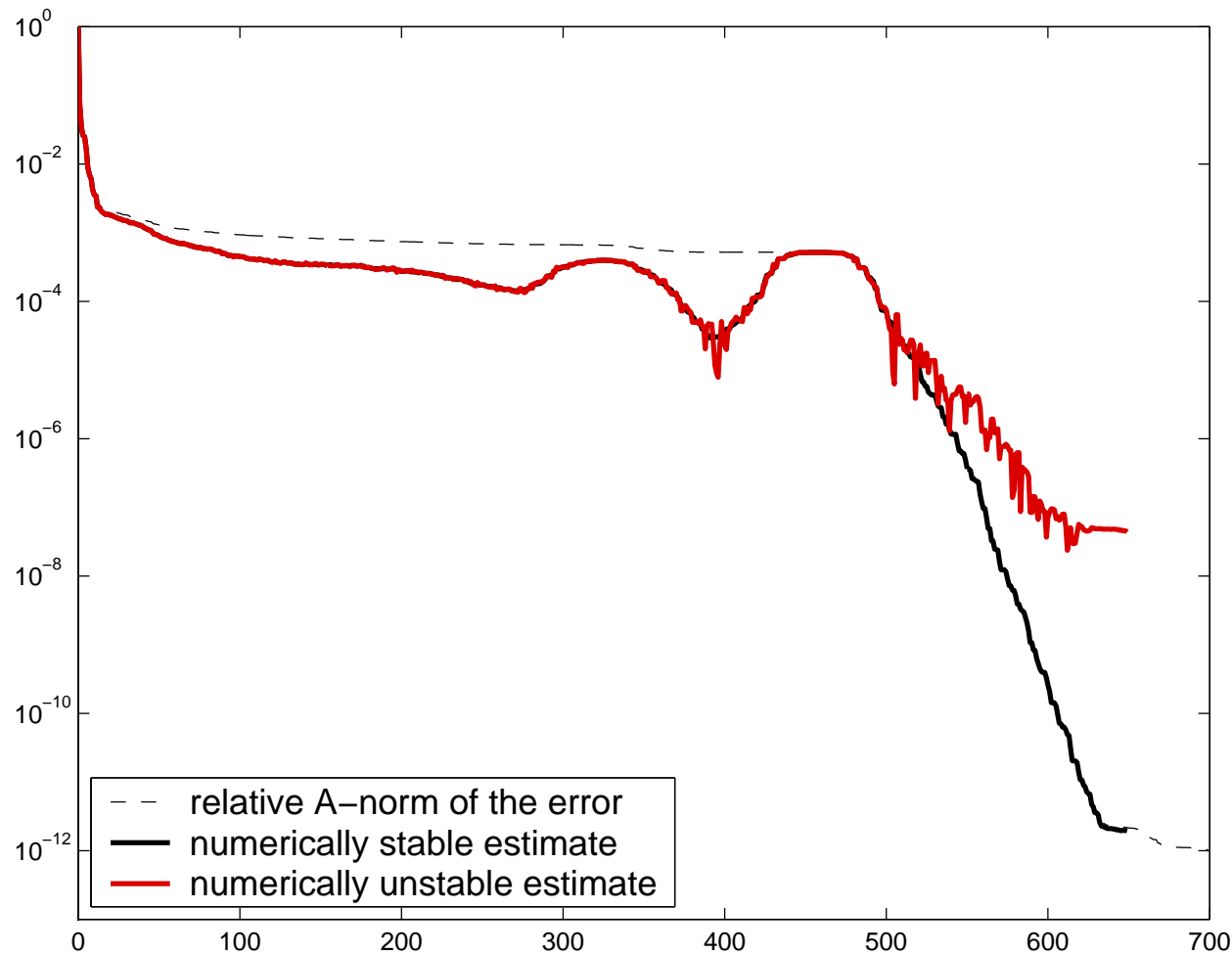
R. Kouhia: Cylindrical shell (Matrix Market), matrix s3dkt3m2,  
**PCG**,  $\kappa(\mathbf{A}) = 3.62e + 11$ ,  $n = 90499$ ,  $d = 200$ ,  $\mathbf{L} = \text{cholinc}(\mathbf{A}, 0)$ .





# Estimating the relative $\mathbf{A}$ -norm of the error

R. Kouhia: Cylindrical shell (Matrix Market), matrix s3rmt3m3,  
**PCG**,  $\kappa(\mathbf{A}) = 2.40e + 10$ ,  $n = 5357$ ,  $d = 50$ ,  $\mathbf{L} = \text{cholinc}(\mathbf{A}, 1e - 5)$ .

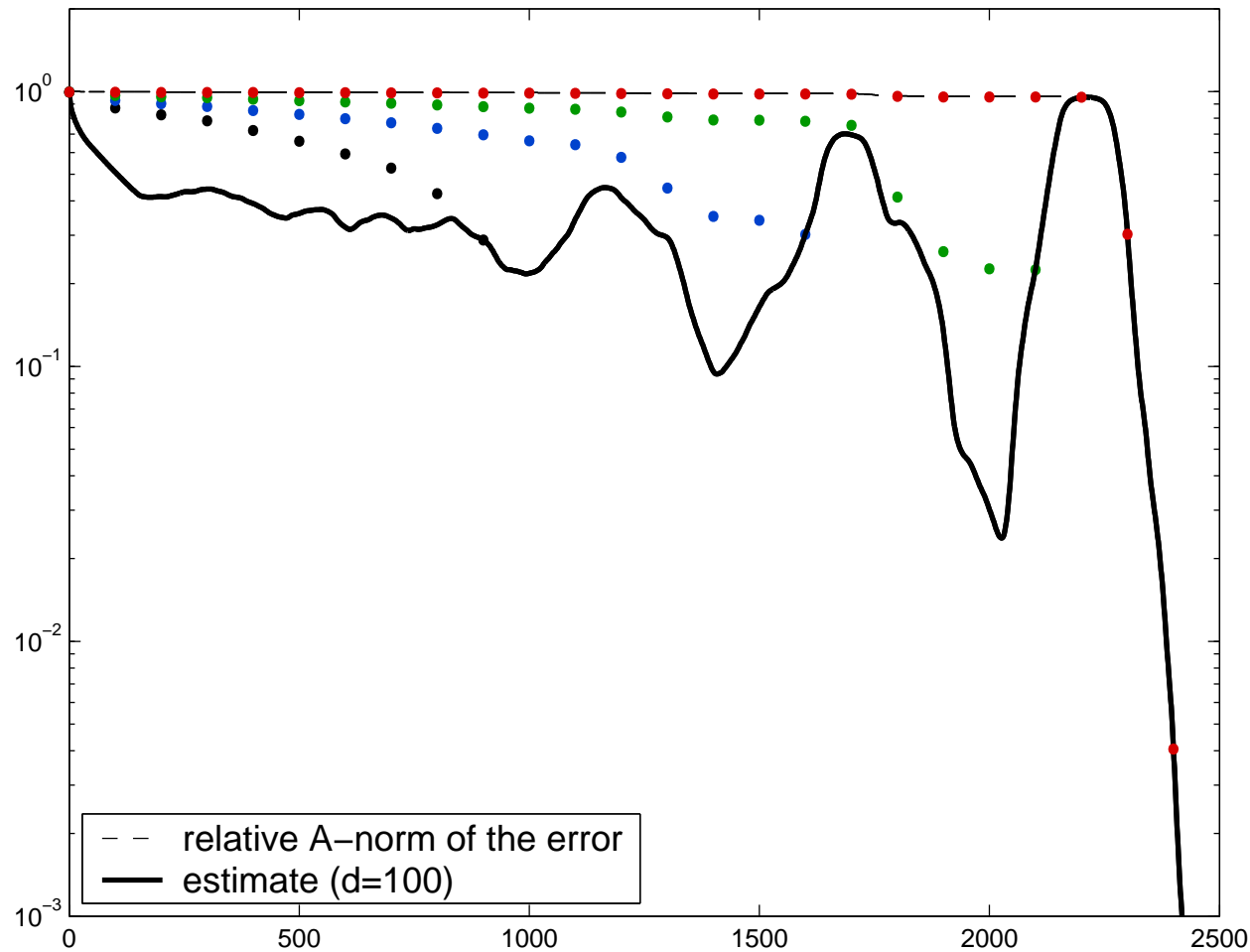






# Reconstruction of the convergence curve

R. Kouhia: Cylindrical shell (Matrix Market), matrix s3dkt3m2,  
**PCG**,  $\kappa(\mathbf{A}) = 3.62e + 11$ ,  $n = 90499$ ,  $d = 100$ ,  $\mathbf{L} = \text{cholinc}(\mathbf{A}, 0)$ .





## 6. Conclusions

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- Various formulas (based on Gauss quadrature) are **mathematically equivalent** to the formulas present (but somehow hidden) in the original Hestenes and Stiefel paper.
- Hestenes and Stiefel estimate is very simple, it can be computed almost for free and it has been proved **numerically stable**.
- We suggest the estimates  $\nu_{j,d}^{1/2}$  and  $\rho_{j,d}^{1/2}$  to be incorporated into any **software realizations** of the CG and PCG methods.
- The estimates are tight if the  $\mathbf{A}$ -norm of the error **reasonably decreases**.

**Open problem:** The adaptive choice of the parameter  $d$ .



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Thank you for your attention!

**More details can be found in**

**Strakoš, Z. and Tichý, P.**, On error estimation in the Conjugate Gradient method and why it works in finite precision computations, Electron. Trans. Numer. Anal. (ETNA), Volume 13, pp. 56-80, 2002.

**Strakoš, Z. and Tichý, P.**, Simple estimation of the  $A$ -norm of the error in the Preconditioned Conjugate Gradients, submitted to BIT Numerical Mathematics, 2004.

`http://www.cs.cas.cz/~strakos,`

`http://www.cs.cas.cz/~tichy`