

# Disjunction and Existence Property in Inquisitive Logic

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The system **InqBQ** ([1], [4], [3]) generalizes **FOL** (first order classical logic) to study *dependencies* between **FOL** structures in a similar fashion to Dependence Logic ([5]) and other logics based on team semantics ([2], [6]). In this paper we introduce several model theoretic constructions useful to study the entailment relation of **InqBQ**, and prove the disjunction and existence for the classical fragment of the logic (presented in [3]).

## GENERALIZING FOL SEMANTICS

In the rest of the paper with  $\Sigma = \{f, \dots; R, \dots\}$  we indicate a fixed **FOL** signature.

**Definition** (Skeleton of a model). Given  $M = \langle D^M; f^M, \dots; R^M, \dots; \sim^M \rangle$  a **FOL** structure (note that we introduce here an extensional equality  $\sim^M$ , i.e. a congruence wrt  $f^M$  and  $R^M$ ) we define its **skeleton** as the tuple  $\text{Sk}(M) = \langle D^M; f^M, \dots \rangle$  consisting of the domain and the interpretation of the function symbols.

**Definition** (Information model). An **information model** is a tuple  $\mathcal{M} = \langle M_w | w \in W^\mathcal{M} \rangle$  where the  $M_w$  are **FOL** structures sharing the same skeleton:  $\forall w, w'. \text{Sk}(M_w) = \text{Sk}(M_{w'})$ .

Conceptually, an information model represents a *collection of possible states of affairs* and we can represent a body of information by selecting the structures compatible with it.

**Definition** (Info state). Given a model  $\mathcal{M}$  we call a subset of the structures that compose it an **info state**:  $s \subseteq W$  (modulo a natural identification). We call a model  $\mathcal{M}_s = \langle M_w | w \in s \rangle$  for  $s \subseteq W^\mathcal{M}$  a **submodel of  $\mathcal{M}$** .

**Definition** (Support semantics). Let  $\mathcal{M}$  be a model,  $s$  an info state of  $\mathcal{M}$  and  $g: \text{Var} \rightarrow D^\mathcal{M}$  a valuation. Let  $\alpha$  be a **FOL** formula. We define the support relation by the following inductive clauses. As a notational convention, we will omit  $s$  if  $s = W^\mathcal{M}$ .

We say that a theory  $\Gamma$  entails a formula  $\alpha$  (notation  $\Gamma \models \alpha$ ) if and only if for every tuple  $\langle \mathcal{M}, s, g \rangle$  that supports  $\Gamma$ , this supports also  $\alpha$ .

**Lemma** (Properties of the support semantics for **FOL** formulas).

**Flatness:**  $\mathcal{M}, s \models_g \alpha \iff \forall w \in s. \mathcal{M}, \{w\} \models_g \alpha$ .

**Classical World Support:**  $\mathcal{M}, \{w\} \models_g \alpha \iff M_w \models_g^{\text{FOL}} \alpha$ .

**Classical Validity Preservation:**  $\Gamma \models \alpha \iff \Gamma \models^{\text{FOL}} \alpha$ .

## ADDING NEW OPERATORS TO THE LOGIC

Defined this generalized semantics, we can now introduce new logical operators to describe *connections and relations between models sharing the same skeleton*. We consider here **the logic InqBQ** obtained by adding the **operator**  $\vee$  and the **quantifier**  $\exists$ , and their associated semantical clauses.

$$\begin{aligned} \mathcal{M}, s \models_g \perp &\iff s = \emptyset \\ \mathcal{M}, s \models_g [t_1 = t_2] &\iff \forall w \in s. M_w \models_g^{\text{FOL}} [t_1 = t_2] \\ \mathcal{M}, s \models_g R(\bar{t}) &\iff \forall w \in s. M_w \models_g^{\text{FOL}} R(\bar{t}) \\ \mathcal{M}, s \models_g \phi \wedge \psi &\iff \mathcal{M}, s \models_g \phi \text{ and } \mathcal{M}, s \models_g \psi \\ \mathcal{M}, s \models_g \phi \rightarrow \psi &\iff \forall t \subseteq s. \text{ if } \mathcal{M}, t \models_g \phi \\ &\quad \text{then } \mathcal{M}, t \models_g \psi \\ \mathcal{M}, s \models_g \forall x. \phi &\iff \forall d \in D^\mathcal{M}. \mathcal{M}, s \models_{g[x \mapsto d]} \phi \end{aligned}$$

$$\mathcal{M}, s \models_g \phi \vee \psi \iff \mathcal{M}, s \models_g \phi \text{ or } \mathcal{M}, s \models_g \psi$$

(a disjunct holds at the *whole state*)

$$\mathcal{M}, s \models_g \exists x. \phi \iff \exists d \in D^\mathcal{M}. \mathcal{M}, s \models_{g[x \mapsto d]} \phi$$

(an element is a *uniform* witness of  $\phi$  at  $s$ )

**Lemma (Downward Closure).**  $\mathcal{M}, s \models_g \phi$  and  $t \subseteq s$ , then  $\mathcal{M}, t \models_g \phi$ .

Note that *flatness holds exactly for those formulas  $\phi$  which are semantically equivalent to a FOL formula* ([3]).

### DISJUNCTION AND EXISTENCE PROPERTIES

**Theorem.** Let  $\Gamma$  be a FOL theory and  $\alpha$  a FOL formula. Then:

**Disjunction Property:** If  $\Gamma \models \phi \vee \psi$ , then  $\Gamma \models \phi$  or  $\Gamma \models \psi$ .

**Existence Property:** If  $\Gamma \models \exists x.\phi(x)$ , then  $\Gamma \models \phi(t)$  for some term  $t$ .

The proof of this theorem is based on the introduction of some relevant model-theoretic constructions.

**The  $\oplus$  operator:** We can define an operator  $\oplus$  such that, given a set of models  $\{\mathcal{M}_i | i \in I\}$ , it produces a model  $\oplus_{i \in I} \mathcal{M}_i$  with the following properties

$$\mathcal{M}_i \not\models \phi \implies \oplus_{i \in I} \mathcal{M}_i \not\models \phi \quad \forall i \in I. \mathcal{M}_i \models \alpha \iff \oplus_{i \in I} \mathcal{M}_i \models \alpha \text{ for } \alpha \text{ classical}$$

This construction strongly relies on *downward closure* and *flatness* for classical formulas.

**Characteristic model of  $\Gamma$ :** Consider a classical theory  $\Gamma$ . For every non entailment  $\Gamma \not\models \phi$  we can select a model  $\mathcal{M}_\phi$  that is a *witness* of it, meaning  $\mathcal{M}_\phi \models_{g_\phi} \Gamma$  and  $\mathcal{M}_\phi \not\models_{g_\phi} \phi$ . If we define now  $\mathcal{M}_\Gamma = \oplus_{\Gamma \not\models \phi} \mathcal{M}_\phi$ , by the property of  $\oplus$  we obtain  $\mathcal{M}_\Gamma \models \psi \iff \Gamma \models \psi$ .

Note that this model can be used to easily prove the disjunction property:

$$\Gamma \models \phi \vee \psi \iff \mathcal{M}_\Gamma \models \phi \vee \psi \iff \mathcal{M}_\Gamma \models \phi \text{ or } \mathcal{M}_\Gamma \models \psi \iff \Gamma \models \phi \text{ or } \Gamma \models \psi$$

**Blow-up model:** given a model  $\mathcal{M}$  we can define an elementarily equivalent model  $\mathcal{BM}$  (the **blow-up of  $\mathcal{M}$** ) whose domain is  $\mathcal{T}\Sigma(D^\mathcal{M})$ , the free algebra of terms in the extended signature  $\Sigma(D^\mathcal{M})$  obtained by adding to  $\Sigma$  a fresh constant symbol for every element of  $D^\mathcal{M}$ . In this step, the intensional equality plays a fundamental role.

**Permutation models:** given a model  $\mathcal{M}$  and a permutation of its elements  $\sigma \in \mathfrak{S}(D^\mathcal{M})$ , we can naturally extend such permutation to  $\mathcal{T}\Sigma(D^\mathcal{M})$ . Using this, we can define a model  $\mathcal{B}^\sigma \mathcal{M}$  by *permuting the names of the elements of  $\mathcal{BM}$  according to  $\sigma$* .

Note that this operation *preserves skeletons* ( $\text{Sk}(\mathcal{BM}) = \text{Sk}(\mathcal{B}^\sigma \mathcal{M})$ ) and that *a closed term  $t$  of  $\Sigma(D^\mathcal{M})$  is fixed under every permutation  $\sigma$  iff  $t$  is a closed term of  $\Sigma$* . These two properties (of great importance for the proof of the existence property) wouldn't hold if the permutation was applied directly to  $\mathcal{M}$ , thus the necessity of defining the model  $\mathcal{BM}$ .

**Lemma.**  $\mathcal{B}^\sigma \mathcal{M} \models \phi(\sigma(d_1), \dots, \sigma(d_n)) \iff \mathcal{BM} \models \phi(d_1, \dots, d_n) \iff \mathcal{M} \models \phi(d_1, \dots, d_n)$

**The full permutation model:** Consider now the model  $\mathcal{M}_\Gamma$ . As the action of a permutation  $\sigma \in \mathfrak{S}(D^{\mathcal{M}_\Gamma})$  preserves the skeleton of  $\mathcal{B}(\mathcal{M}_\Gamma)$ , we can consider the new model  $\mathfrak{S}(\mathcal{M}_\Gamma) = \{M | \exists \sigma. M \in \mathcal{B}^\sigma(\mathcal{M}_\Gamma)\}$ . By building  $\mathcal{M}_\Gamma$  in a suitable way, we can obtain the following two properties:

$\mathfrak{S}(\mathcal{M}_\Gamma) \models \phi \iff \Gamma \models \phi$ : since  $\mathfrak{S}(\mathcal{M}_\Gamma) \models \Gamma$  can be tested on single worlds by *flatness*, and  $\mathcal{B}(\mathcal{M}_\Gamma)$  is a submodel of  $\mathfrak{S}(\mathcal{M}_\Gamma)$ .

$\mathfrak{S}(\mathcal{M}_\Gamma) \models \exists x.\phi(x) \implies \mathfrak{S}(\mathcal{M}_\Gamma) \models \phi(t)$  for some closed  $t$ : the intuitive reason being that the role of two elements can be *swapped* in the model  $\mathfrak{S}(\mathcal{M}_\Gamma)$  as long as they are not fixed by every permutation  $\sigma$ . From this we obtain that, if there exists an element without the property  $\phi$ , then every element that is not the interpretation of a closed term of  $\Sigma$  does not have the property.

Note that this model can be used to easily prove the existence property:

$$\Gamma \models \exists x.\phi(x) \iff \mathfrak{S}(\mathcal{M}_\Gamma) \models \exists x.\phi(x) \iff \exists t \text{ closed. } \mathfrak{S}(\mathcal{M}_\Gamma) \models \phi(t) \iff \exists t \text{ closed. } \Gamma \models \phi(t)$$

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