

Product Kernel Regularization Network

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ICANNGA, 21st - 23rd March 2005,
Coimbra, Portugal

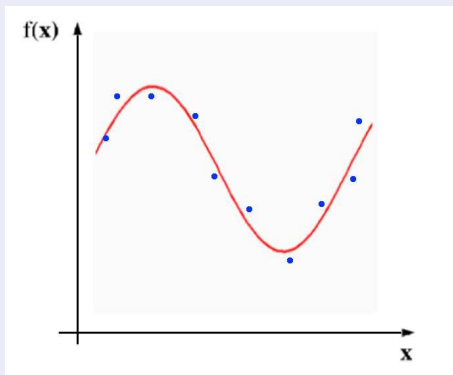
Outline

- Introduction
 - Learning from examples
- Theoretical background
 - Learning from data as minimization of functionals
 - Reproducing Kernel Hilbert Spaces
- Product Kernel Regularization Network
 - Motivation
 - Product kernel
 - Learning algorithm
 - Model selection
- Experimental results
 - Benchmark comparison
 - Flow rate prediction
- Conclusion

LEARNING FROM EXAMPLES

Problem statement

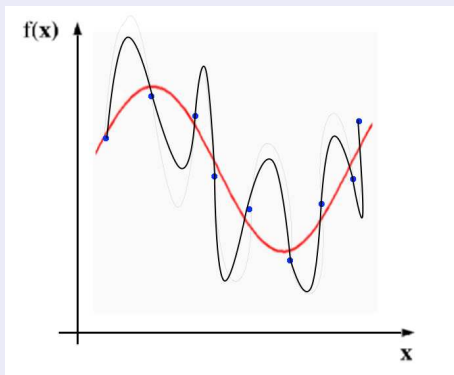
- **Given:** set of data samples $\{(\vec{x}_i, y_i) \in R^d \times R\}_{i=1}^N$
- **Our goal:** recover the unknown function or find the best estimate of it



LEARNING FROM EXAMPLES

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REGULARIZATION THEORY

Empirical Risk Minimization:

- find f that minimizes $H[f] = \frac{1}{N} \sum_{i=1}^N (f(\vec{x}_i) - y_i)^2$
- generally ill-posed
- choose one solution according to a priori knowledge (*smoothness, etc.*)

Regularization approach

- add a **stabiliser** $H[f] = \frac{1}{N} \sum_{i=1}^N (f(\vec{x}_i) - y_i)^2 + \gamma \Phi[f]$

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Reproducing Kernel Hilbert Space

Definition and properties

- RKHS is a Hilbert space of functions defined over $\Omega \subset \mathbb{R}^d$ with the property that for each $x \in \Omega$ the evaluation functional on \mathcal{H} given by $\mathcal{F}_x : f \rightarrow f(x)$ is bounded. (*Aronszajn, 1950*)
- This implies existence of positive definite symmetric function $K : \Omega \times \Omega \rightarrow \mathbb{R}$ (*kernel function*) such that

$$\mathcal{H} = \mathcal{H}_K = \text{comp} \left\{ \sum_{i=1}^n a_i K_{x_i}; x_i \in \Omega, a_i \in \mathbb{R} \right\},$$

where comp means completion of the set.

Reproducing Kernel Hilbert Space

Application in learning

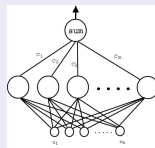
[Poggio, Smale, 2003]

- Data set: $\{(\vec{x}_i, y_i) \in \mathbb{R}^d \times \mathbb{R}\}_{i=1}^N$
- choose a symmetric, positive-definite kernel $K = K(\vec{x}_1, \vec{x}_2)$
- let \mathcal{H}_K be the RKHS defined by K
- define the stabiliser by the norm $\|\cdot\|_K$ in \mathcal{H}_K

$$H[f] = \frac{1}{N} \sum_{i=1}^N (y_i - f(\vec{x}_i))^2 + \gamma \|f\|_K^2$$

- minimise $H[f]$ over $\mathcal{H}_K \longrightarrow$ solution:

$$f(\vec{x}) = \sum_{i=1}^N c_i K_{\vec{x}_i}(\vec{x})$$



PRODUCT KERNEL REGULARIZATION NETWORK

Motivation

- different kernels are suitable for different data types
- data attributes are often of different types (temperature, color, age)

color	temperature	age
red	35.5	34
blue	36.0	56
red	36.9	45
...

PRODUCT KERNEL REGULARIZATION NETWORK

How to deal with attributes of different types?

- preprocessing
- convert everything to real values

Our approach

- divide the attributes to several subsets
- process the subsets separately
- select appropriate kernel for each subset
- allow difference not only in attribute type but also different properties – density, variance

PRODUCT KERNEL REGULARIZATION NETWORK

Product Kernels

[Aronszajn, 1950]

Let F_1 be an RKHS on Ω_1 with kernel K_1 , F_2 an RKHS on Ω_2 with kernel K_2 . Then

$$F = \text{comp} \left\{ \sum_{i=1}^n f_{1,i}(x_1) f_{2,i}(x_2) \right\}$$

is an RKHS on $\Omega_1 \times \Omega_2$ with kernel given by

$$K((x_1, x_2), (y_1, y_2)) = K_1(x_1, y_1) K_2(x_2, y_2),$$

where $x_1, y_1 \in \Omega_1$, $x_2, y_2 \in \Omega_2$.

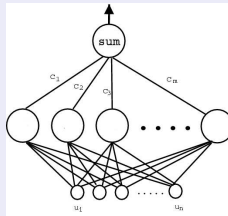
Completion by scalar product:

$$\langle \sum_{i=1}^n f_{1,i}(x_1) f_{2,i}(x_2), \sum_{j=1}^m g_{1,j}(x_1) g_{2,j}(x_2) \rangle = \sum_{i=1}^n \sum_{j=1}^m \langle f_{1,i}, g_{1,j} \rangle_1 \langle f_{2,i}, g_{2,j} \rangle_2$$

PRODUCT KERNEL REGULARIZATION NETWORK

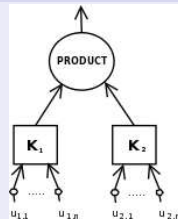
Network structure

- feedforward network with one hidden layer
- hidden layer of product units
- linear output layer



Product unit

- consists of several parts
- each part processes one group of attributes
- each part evaluates its own kernel function



PRODUCT KERNEL REGULARIZATION NETWORKS

Learning algorithm

Input: Data set $\{\vec{u}_1^i, \vec{u}_2^i, \vec{v}^i\}_{i=1}^k \subseteq \mathbb{R}^n \times \mathbb{R}^m \times \mathbb{R}$

Output: Product Kernel Regularization network.

1. Set the centers of kernels:

$$\forall i \in \{1, \dots, k\} : \begin{aligned} \vec{c}_1^i &\leftarrow \vec{u}_1^i \\ \vec{c}_2^i &\leftarrow \vec{u}_2^i \end{aligned}$$

2. Compute the values of weights w_1, \dots, w_k :

$$(k\gamma I + K)\vec{w} = \vec{v},$$

where I is the identity matrix,

$K_{i,j} = K_1(\vec{c}_1^i, \vec{u}_1^j) \cdot K_2(\vec{c}_2^i, \vec{u}_2^j)$, and $\vec{v} = (v_1, \dots, v_k)$, $\gamma > 0$.

MODEL SELECTION

Parameters of proposed algorithm

- kernel type
- kernel parameter(s) (i.e. width for Gaussian)
- regularization parameter γ

How we estimate these parameters?

- kernel type by user
- kernel parameter and regularization parameter by grid search and crossvalidation
- speed-up techniques: grid refining, lazy evaluation

EXPERIMENTS

Methodology

- two disjunct data sets for training and testing
- normalized error function

$$E = 100 \frac{1}{N} \sum_{i=1}^N \|v^i - f(\vec{u}_1^i, \vec{u}_2^i)\|^2,$$

- LAPACK library was used for solving linear systems

Data Tasks

- benchmark – Proben1 data repository
- real life – prediction of flow rate of the river Ploučnice

EXPERIMENTS

Comparison with RN

	PKRN		RN	
	E_{train}	E_{test}	E_{train}	E_{test}
cancer1	2.739	1.816	2.658	1.875
cancer2	2.152	3.516	2.279	3.199
cancer3	2.374	2.798	2.348	2.873
glass1	6.141	8.590	4.899	8.033
glass2	5.269	8.202	4.570	8.317
glass3	3.691	7.411	4.837	7.691

Table: Error values for PKRN and RN on Proben1 data sets.

EXPERIMENTS

Prediction of flow rate

- prediction of the flow rate on the Ploučnice in North Bohemia, from origin (southwest part of the Ještěd hill) to the town Mimoň
- time series containing daily flow and rainfall values
- prediction of the current flow rate based on information from the previous one or two days
- 1000 training samples, 367 testing samples



EXPERIMENTS

Error values of PKRN

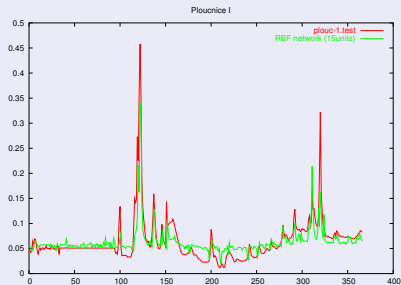
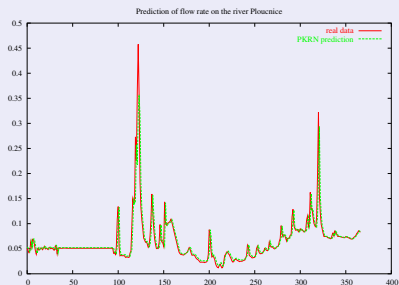
	pl1	pl2
E_{train}	0.057	0.109
E_{test}	0.048	0.097

Comparison with conservative predictor

	PKRN	CP
E_{train}	0.057	0.093
E_{test}	0.048	0.054

EXPERIMENTS

Prediction of flow rate



CONCLUSION

Summary

- product of two kernel functions is a kernel function
- Product Kernel Regularization Network
- its behaviour demonstrated on experiments

Future work

- study properties and usability of other types of kernels
- automatic model selection (including type of kernel function)

Thank you for your attention.

Any questions?